ABB MEASUREMENT & ANALYTICS | OPERATING INSTRUCTION

TZIDC

Digital Positioner

Digital Positioner for the positioning of pneumatically controlled final control elements.

Introduction

The TZIDC is an intelligent digital positioner for communication via HART® within the positioner product range. Unsurpassed shock absorption and vibration compensation from 10 g to 80 Hz distinguishes the TZIDC from other products and guarantees reliable operation in nearly any area under the harshest ambient conditions.

Additional Information

Additional documentation on TZIDC is available for download free of charge at www.abb.com/positioners.
Alternatively simply scan this code:

Table of contents

1 Safety

General information and instructions

These instructions are an important part of the product and must be retained for future reference.
Installation, commissioning, and maintenance of the product may only be performed by trained specialist personnel who have been authorized by the plant operator accordingly. The specialist personnel must have read and understood the manual and must comply with its instructions.
For additional information or if specific problems occur that are not discussed in these instructions, contact the manufacturer.
The content of these instructions is neither part of nor an amendment to any previous or existing agreement, promise or legal relationship.
Modifications and repairs to the product may only be performed if expressly permitted by these instructions.
Information and symbols on the product must be observed. These may not be removed and must be fully legible at all times.
The operating company must strictly observe the applicable national regulations relating to the installation, function testing, repair and maintenance of electrical products.

Warnings

The warnings in these instructions are structured as follows:

⚠ DANGER

The signal word '**DANGER**' indicates an imminent danger. Failure to observe this information will result in death or severe injury.

⚠ WARNING

The signal word '**WARNING**' indicates an imminent danger. Failure to observe this information may result in death or severe injury.

⚠ CAUTION

The signal word '**CAUTION**' indicates an imminent danger. Failure to observe this information may result in minor or moderate injury.

NOTICE

The signal word ***'NOTICE'*** indicates possible material damage.

Note
'**Note**' indicates useful or important information about the product.

… 1 Safety

Intended use

Positioning of pneumatically controlled actuators; designed for mounting on linear and rotary actuators.
The device is designed for use exclusively within the stated values on the name plate and in the data sheet.

- The maximum operating temperature must not be exceeded.
- The maximum ambient temperature must not be exceeded.
- The housing's rating must be observed during operation.

Improper use

The following are considered to be instances of improper use of the device:

- For use as a climbing aid, for example for mounting purposes.
- For use as a bracket for external loads, for example as a support for piping, etc.
- Material application, for example by painting over the housing, name plate or welding/soldering on parts.
- Material removal, for example by spot drilling the housing.

Notes on data safety

This product is designed to be connected to and to communicate information and data via a network interface.
It is operator’s sole responsibility to provide and continuously ensure a secure connection between the product and your network or any other network (as the case may be).
Operator shall establish and maintain any appropriate measures (such as but not limited to the installation of firewalls, application of authentication measures, encryption of data, installation of anti-virus programs, etc.) to protect the product, the network, its system and the interface against any kind of security breaches, unauthorized access, interference, intrusion, leakage and / or theft of data or information.
ABB Automation Products GmbH and its affiliates are not liable for damages and / or losses related to such security breaches, any unauthorized access, interference, intrusion, leakage and / or theft of data or information.

Warranty provisions

Using the device in a manner that does not fall within the scope of its intended use, disregarding this manual, using underqualified personnel, or making unauthorized alterations releases the manufacturer from liability for any resulting damage. This renders the manufacturer's warranty null and void.

Manufacturer’s address

ABB Automation Products GmbH
Measurement & Analytics
Schillerstr. 72
32425 Minden
Germany
Tel: +49 571 830-0
Fax: +49 571 830-1806

Customer service center
Tel: +49 180 5 222 580
Email: automation.service@de.abb.com

2 Use in potentially explosive atmospheres

General requirements

- The ABB positioner has been approved only for appropriate and intended use in standard industrial atmospheres. Any breach of this rule leads to a cancellation of warranty and manufacturer's responsibility!
- Make sure that only devices which comply with the types of protection relevant to the applicable zones and categories are installed.
- All electric equipment has to be suited for the respective intended use.
- In potentially explosive atmospheres, assembly may be conducted only in compliance with locally applicable installation regulations. The following conditions have to be observed (incomplete):
  - Assembly and maintenance may only be conducted if there is no explosion hazard in the area and you have a hot work permit.
  - The TZIDC may be operated in a fully mounted and intact housing only.

Commissioning, Installation

The ABB positioner has to be mounted in a major system. Depending on the degrees of IP-protection, an interval for cleaning the equipment (dust settlement) has to be defined. Strict care has to be taken that only devices which comply with the types of protection relevant to the applicable zones and categories is installed. When installing the device, the locally applicable installation regulations, such as EN 60079-14, must be observed.
Other important facts to be observed:

- The electric circuits of the positioner must be put into operation in all zones by persons qualified in accordance with TRBS 1203. The details on the type label are mandatory for doing this.
- The device has been designed in accordance with IP 65 (optionally IP 66) and must be protected accordingly against adverse ambient conditions.
- The EC Type Examination Certificate has to be taken into account, including any special conditions defined therein.
- The device may only be used in accordance with its intended use.
- The device may only be connected when de-energized.
- The potential equalization of the system must be established in accordance with installation regulations applicable in the respective country (VDE 0100, part 540, IEC 364-5-54).
- Circulating currents must not be guided through the housing!
- Make sure that the housing is properly installed and that its IP rating has not been compromised.

Notes for operation

- The positioner must be integrated in the local potential equalization system.
- Only either intrinsically safe or non-intrinsically safe circuits may be connected. A combination is not permit - ted.
- If the positioner is operated with non-intrinsically safe circuits, later use for the intrinsic safety type of protection is not permitted.

Use, operation

The TZIDC is approved for proper and intended use only. In case of non-compliance, the warranty and manufacturer’s liability do no longer apply!

- Only those auxiliary components which fulfill all the requirements of European and national standards may be used in potentially explosive atmospheres.
- The ambient conditions specified in the operating instruction must be strictly followed.
- The TZIDC is approved for proper and intended use in standard industrial atmospheres only. Where aggressive substances are present in the air, the manufacturer has to be consulted.

… 2 Use in potentially explosive atmospheres

Maintenance, repair

Definition of terms according to IEC 60079-17:

Maintenance

Defines a combination of actions performed to maintain or restore the condition of an item such that the item meets the requirements of the relevant specification and performs its required functions.

I ¬Analyzer module without electronics module (power supply):

Defines an action which involves careful inspection of an item (either without disassembly or with partial disassembly, as required) supplemented by measurements, aimed at achieving a reliable conclusion regarding the condition of the item.

Visual inspection

Defines an inspection which identifies defects which are visible to the naked eye, such as missing screws, without the use of access equipment and tools.

Close inspection

Defines an inspection which encompasses the aspects covered by a visual inspection and in addition, identifies defects such as loose screws, which can only be detected with the use of access equipment (e.g. steps) and tools.

Detailed inspection

Defines an inspection which encompasses the aspects covered by a close inspection and in addition, identifies defects, such as loose connections, which can only be detected by opening the housing and / or by using tools and test devices, as needed.

- Maintenance and exchange work may be conducted by qualified specialists only, i.e., qualified personnel in accordance with TRBS 1203 or similar.
- Only those auxiliary components which fulfill all the requirements of European and national guidelines and regulations may be used in potentially explosive atmospheres.
- Maintenance works that require disassembly of the system may only be performed in non-hazardous areas. If that is not possible, however, the usual precautions have to be ensured according to local regulations.
- Components may only be replaced by original spare parts which are therefore approved for use in potentially explosive atmospheres.
- The device must be regularly cleaned when used in potentially explosive atmospheres. The intervals must be defined by the operator in compliance with the ambient conditions present at the operating location.
- After all maintenance and repair work has been completed, any barriers and plates removed for that purpose must be put back in their original place.
- The flameproof joints differ from the tables of IEC 60079-1 and may be repaired by the manufacturer only.

Activity	Visual inspection (every 3 months)	Close inspection (every 6 months)	Detailed inspection (every 12 months)
Visual inspection of the positioner for integrity, removal of dust deposits	●		
Inspection of electric installation for integrity and proper operation			●
Inspection of the entire installation	Responsibility of the operator		

Product identification

Depending on the type of explosion protection, Ex-marking is attached to the positioner on the right, next to the main name plate.
This indicates the level of explosion protection and the device's relevant Ex certificate.

Marking (name plate)

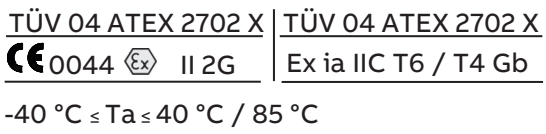


Figure 1: Marking

Note
A legible marking showing the type of protection required for the intended area of application must be affixed to the device before it is put into operation for the first time.

Preconditions for safe operation of the positioner

⚠ DANGER

Risk of explosion due to hot parts
Hot parts inside the device pose an explosion hazard.
- Never open the device immediately after switch-off.
- A waiting time of at least four minutes should be observed before opening the device.

When using in hazardous areas, observe the following points:
- Observe the specification and special conditions applicable for the device in accordance with the relevant valid certificate.
- Manipulation of the device in any form by the user is not permitted. Only the manufacturer or an explosion protection specialist may modify the device
- The IP 65 / NEMA 4x IP rating is only achieved if the splash guard is screwed in place. Operating the unit without splash guard cap is prohibited.
- The device may only be operated using instrument air that is free from oil, water and dust. The use of flammable gas, oxygen, or oxygen-enriched gas is not permitted.

Cable gland
Limited temperature range of the M20 × 1.5 plastic cable gland for explosion protection variants.
The permissible ambient temperature range of the cable gland is −20 to 80 °C (−4 to 176 °F). When using the cable gland, make sure that the ambient temperature is within this range. The cable gland must be installed in the housing with a tightening torque of 3.8 Nm. When installing the connection of the cable gland and cable, check for tightness to ensure that the required IP rating is met.

… 2 Use in potentially explosive atmospheres

ATEX / EAC TR-CU-012

(limited functionality with EAC TR-CU-012)

ATEX Ex i

Ex marking	
Marking	II 2 G Ex ia IIC T6 resp. T4 Gb
	II 2 G Ex ib IIC T6 resp. T4 Gb
Type Examination Test Certificate	TÜV 04 ATEX 2702 X
Type	Intrinsically safe equipment
Device class	II 2 G
Standards	EN 60079-0:2012
	EN 60079-11:2012

Temperature Data

Device group II 2 G	
Temperature class	**Ambient temperature Ta**
T4	−40 to 85 °C
T5	−40 to 50 °C
T6*	−40 to 40 °C*

* When using the 'Limit monitor' plug−in module in temperature class T6, the maximum permissible ambient temperature range is −40 to 35 °C.

Electrical Data

In intrinsically safe explosion protection types Ex ib IIC / Ex ia IIC or Ex ia IIIC, only for connection to a certified intrinsically safe circuit.

Current circuit (terminal)	**Electrical information (maximum values)**	
Signal circuit (+11 / −12)	U_i = 30 V I_i = 320 mA P_i = 1.1 W	C_i = 6.6 nF L_i = negligibly small
Contact input (+81 / −82)	U_i = 30 V I_i = 320 mA P_i = 1.1 W	C_i = 4.2 nF L_i = negligibly small
Switch output (+83 / −84)	U_i = 30 V I_i = 320 mA P_i = 500 mW	C_i = 4.2 nF L_i = negligibly small
Mechanical limit monitor, (Pepperl & Fuchs SJ2-SN) (Limit1: +51 / −52), (Limit2: +41 / −42)	U_i = 20 V C_i = ≤ 30 nF L_i = ≤ 100 µH I_i = 25 mA P_i = 1.1 W	
Plug-in module for limit monitor (+51 / −52) (+41 / −42)	U_i = 30 V I_i = 320 mA P_i = 250 mW	C_i = 3.7 nF L_i = negligibly small
Plug-in module for analog position feedback (+31 / −32)	U_i = 30 V I_i = 320 mA P_i = 1.1 W	C_i = 6.6 nF L_i = negligibly small
Interface with the TZIDC Remote Sensor (X2-2: +Uref, X3-2: GND, X3-1: signal)	U_0 = 5.4 V I_0 = 74 mA P_0 = 100 mW C_i = negligibly small L_i = negligibly small	Ex ia or Ex ib type of protection IIC: L_0 = 5 mH C_0 = 2 µF IIB: L_0 = 5 mH C_0 = 10 µF
Local communication interface (LCI)	Only for connection to a programming device using an ABB LCI adapter (Um ≤ 30 V DC) outside the hazardous area.	

Special conditions

- Prevent electrostatic charging due to propagating brush discharge when the equipment is used for applications involving combustible dust.

IECEx Ex i

Ex marking	
Marking	Ex ia IIC T6 or T4 Gb
	Ex ib IIC T6 or T4 Gb
Type Examination Test Certificate	IECEx TUN 04.0015X
Type	Intrinsic safety 'i'
Standards	IEC 60079-0:2011
	IEC 60079-11:2011

Temperature Data

Temperature class	**Ambient temperature Ta**	
	TZIDC Ex ia IIC	**TZIDC Ex ib IIC**
T4	−40 to 85 °C	−40 to 85 °C
T6*	−40 to 40 °C*	−40 to 40 °C

* When using the 'Limit monitor' plug−in module in temperature class T6, the maximum permissible ambient temperature range is −40 to 35 °C.

Electrical Data

In 'intrinsically safe Ex ib IIC / Ex ia IIC' type of protection, only for connection to a certified intrinsically safe circuit.

Current circuit (terminal)	**Electrical information (maximum values)**	
Signal circuit	U_i = 30 V	C_i = 6.6 nF
(+11 / −12)	I_i = 320 mA	L_i = negligibly small
	P_i = 1.1 W	
Contact input	U_i = 30 V	C_i = 4.2 nF
(+81 / −82)	I_i = 320 mA	L_i = negligibly small
	P_i = 1.1 W	
Switch output	U_i = 30 V	C_i = 4.2 nF
(+83 / −84)	I_i = 320 mA	L_i = negligibly small
	P_i = 500 mW	
Local communication interface (LCI)	Only for connection to a programming device using an ABB LCI adapter (Um ≤ 30 V DC) outside the hazardous area.	

The following modules may be operated as an option:

Current circuit (terminal)	**Electrical information (maximum values)**	
Plug-in module for limit monitor (+51 / −52) (+41 / −42)	U_i = 30 V I_i = 320 mA P_i = 250 mW	Ci = 3.7 nF Li = negligibly small
Plug-in module for analog position feedback (+31 / −32)	U_i = 30 V I_i = 320 mA P_i = 1.1 W	Ci = 6.6 nF Li = negligibly small

Special conditions

- For the 'Limit monitor with proximity switches' circuit, measures outside of the device must be implemented to prevent the rated voltage from being up-scaled by more than 40 % due to transient disturbances.
- It is only permissible to connect, disconnect, and switch live circuits during installation or maintenance, or for the purpose of carrying out repairs. Note: It is considered very unlikely that a hazardous atmosphere would be present in Zone 2 at the same time that installation, maintenance or repair work was being carried out.
- Only non-flammable gases may be used for pneumatic power supply.
- Only use suited cable entries that meet the requirements of EN 60079-15.

… 2 Use in potentially explosive atmospheres

FM / CSA

(limited functionality)

CSA International

Certificate	
Certificate	1052414
Class 2258 02	PROCESS CONTROL EQUIPMENT – For Hazardous Locations
Class 2258 04	PROCESS CONTROL EQUIPMENT – Intrinsically Safe, Entity – For Hazardous Locations

Electric data

Model TZIDC, P/N V18345-x0x2x2xx0x Intelligent Positioner	
For use in	Class I, Div 2, Groups A, B, C and D Class II, Div 2, Groups E, F, and G Class III, Enclosure Type 4X
Input rated	30 V DC; max. 4 to 20 mA
Max output pressure	90 psi 80 psi (Marine version)
Max. ambient temperature	85 °C

Model TZIDC, P/N V18345-x0x2x2xx0x Intelligent Positioner intrinsically safe with entity parameters of:		
For use in	Class I, Div 1, Groups A, B, C and D; Class II, Div 1, Groups E, F and G Class III, Enclosure Type 4X:	
Terminals 11 / 12	U_{max} = 30 V I_{max} = 104 mA	C_i = 6.6 nF L_i = 0 µH
Terminals 81 / 82	U_{max} = 30 V I_{max} = 110 mA	C_i = 4.2 nF L_i = 0 µH
Terminals 83 / 84	U_{max} = 30 V I_{max} = 90 mA	C_i = 4.2 nF L_i = 0 µH
Terminals 31 / 32	U_{max} = 30 V I_{max} = 110 mA	C_i = 6.6 nF L_i = 0 µH
Terminals 41 / 42 and 51 / 52	U_{max} = 30 V I_{max} = 96 mA	C_i = 3.7 nF L_i = 0 µH
Terminals Limit 2 41 / 42 and Limit 1 51 / 52	U_{max} = 15.5 V I_{max} = 52 mA	C_i = 20 nF L_i = 30 µH

Note

- The ‘x’ in P/N denotes minor mechanical variations or optional features.
- Local communication interface (LCI) shall not be used in hazardous location.
- Each pair of conductors of each intrinsic safety circuit shall be shielded.
- See FM installation drawing No. 901064 for Details.

CSA Certification Record

Certificate	
Certificate	1649904 (LR 20312)
Class 2258 04	PROCESS CONTROL EQUIPMENT – Intrinsically Safe, Entity – For Hazardous Locations

Electric data

Model TZIDC, P/N V18345-x0x2x2xx0x Intelligent Positioner		
For use in	Class I, Div 1, Groups A, B, C and D; Class II, Div 1, Groups E, F, and G, Class III, Div 1, Enclosure Type 4X	
Input rated	30 V DC; max.4 to 20 mA	
Output pressure	80 psi (Marine version)	
Intrinsically safe with entity parameters of:		
Terminals 11 / 12	U_{max} = 30 V I_{max} = 104 mA	C_i = 6.6 nF L_i = 0 µH P_i = 1 W
Terminals 81 / 82	U_{max} = 30 V I_{max} = 110 mA	C_i = 3.7 nF L_i = 0 µH P_i = 1 W
Terminals 83 / 84	U_{max} = 30 V I_{max} = 90 mA	C_i = 3.7 nF L_i = 0 µH P_i = 1 W
Terminals 31 / 32	U_{max} = 30 V I_{max} = 110 mA	C_i = 6.6 nF L_i = 0 µH P_i = 1 W
Terminals 41 / 42 and 51 / 52	U_{max} = 30 V I_{max} = 96 mA	C_i = 3.7 nF L_i = 0 µH P_i = 1 W
Terminals Limit 2 41 / 42 and Limit 1 51 / 52	U_{max} = 15.5 V I_{max} = 52 mA	C_i = 20 nF L_i = 30 µH P_i = 1 W
When installed per installation Drawing No 901064:		
Temperature Code	T4	
Max. Ambient temperature	85 °C	

Note

- The ‘x’ in P/N denotes minor mechanical variations or optional features.
- Local communication interface LCI shall not be used in hazardous location.
- Each pair of conductors of each intrinsic safety circuit shall be shielded.
- See FM installation drawing No. 901064 for Details.

FM Approvals

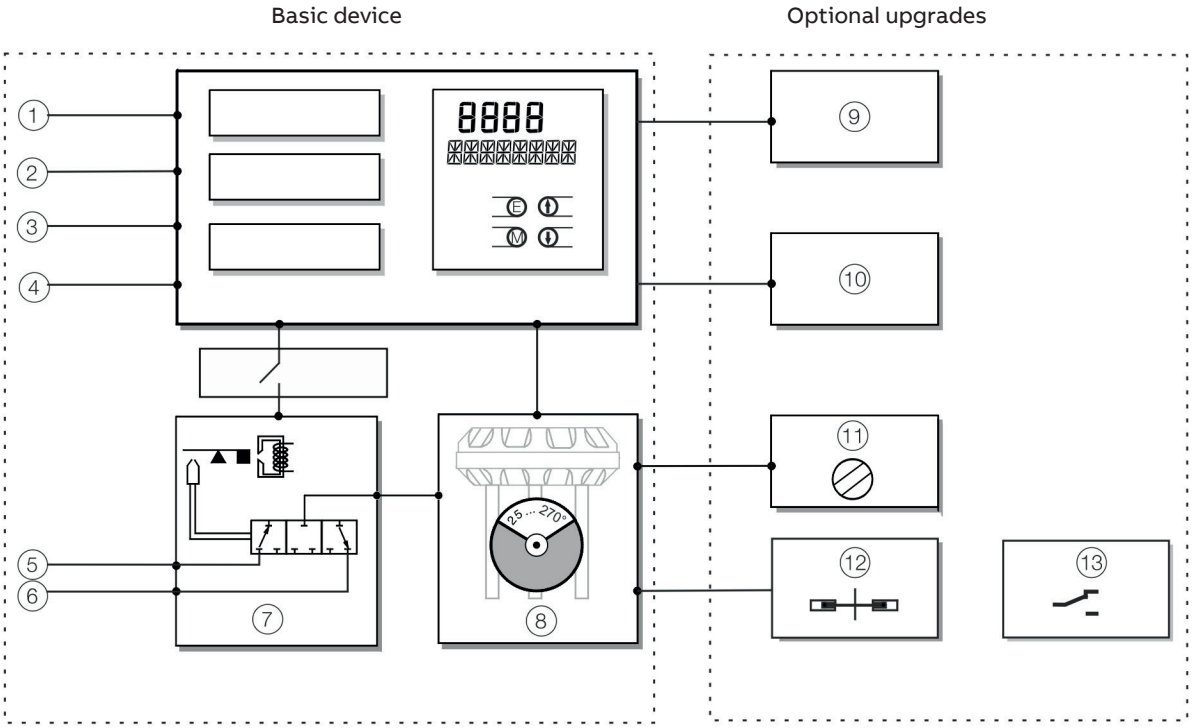
TZIDC Positioner, Model V18345-a0b2c2de0f
IS/I,II,III/1/ABCDEFG/T4 Ta = 85 °C – 901064/7/4; Enity;
NI/I/2/ABCD/T4 Ta = 85 °C;
S/II,III/2/FG/T4 Ta =85 °C; Type 4X
Max Enity Parameters: Per Control Drawings

a Case/mounting – 1, 2, 3, 4 or 9
b Input/communication port – 1 or 2
c Output/safe protection – 1, 2, 4 or 5
d Option modules for analog or digital position feedback – 0, 1, 3 or 5
e Mechanical kit (proximity swiches) for digital position feedback (option) – 0, 1 or 3
f Design (varnish/coding) – 1 or 2

See FM installation drawing No. 901064 for Details.

3 Design and function

Schematic diagram



① LCI plug
② Setpoint signal 4 to 20 mA
③ Binary input
④ Binary output
⑤ Supply air: 1.4 to 6 bar (20 to 90 psi)
⑥ Exhaust
⑦ I/P module with 3/3-way valve
⑧ Position sensor
⑨ Plug-in module analog feedback (4 to 20 mA)
⑩ Plug-in module digital feedback
⑪ Installation kit for mechanical position indication
⑫ Limit value monitor with proximity switches
⑬ Limit value monitor with 24 V-microswitches

Figure 2: Schematic diagram of the positioner

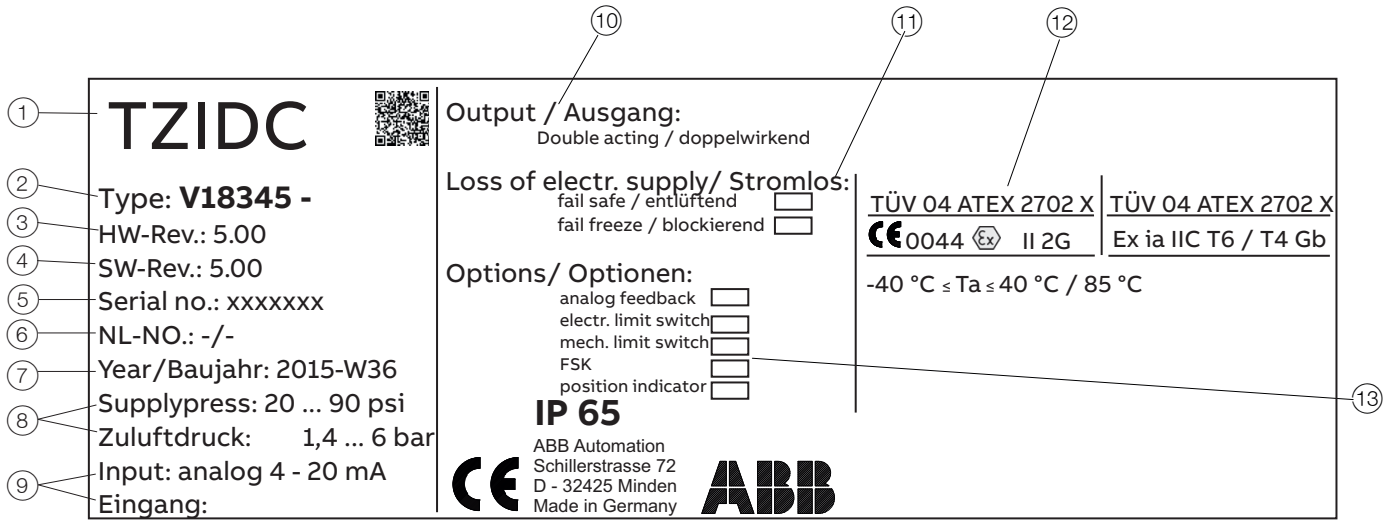
Note
With optional extensions, either the 'Limit value monitor with proximity switches' ⑫ or the 'Limit value monitor with 24 V-microswitches' ⑬ can be used. In both cases though, the mechanical position indication ⑪ must be installed.

Principle of operation

The TZIDC is an electronically configurable positioner with communication capabilities designed for mounting on pneumatic linear or rotary actuators.
Fully automatic determination of the control parameters and adaptation to the positioner allow for considerable time savings as well as optimum control behavior.

4 Product identification

Name plate



1. Full type designation
2. Master number
3. Hardware rev.
4. Software rev.
5. Serial number
6. Code for customer-specific design
7. Year of manufacture
8. Supply air pressure
9. Input signal
10. Mode of action of the pneumatic system
11. Reaction in case of voltage failure
12. Ex variant
13. Additional options

Figure 3: Name plate (example)

5 Transport and storage

Inspection

Check the devices immediately after unpacking for possible damage that may have occurred from improper transport. Details of any damage that has occurred in transit must be recorded on the transport documents.
All claims for damages must be submitted to the shipper without delay and before installation.

Transporting the device

Observe the following instructions:

- Do not expose the device to humidity during transport. Pack the device accordingly.
- Pack the device so that it is protected against vibrations during transport, for example, by using air-cushioned packing.

Storing the device

Bear the following points in mind when storing devices:

- Store the device in its original packaging in a dry and dust-free location. The device is also protected by a desiccant in the packaging.
- The storage temperature should be between −40 to 85 °C (−40 to 185 °F).
- Avoid storing the device in permanent direct sunlight.
- In principle, the devices may be stored for an unlimited period. However, the warranty conditions stipulated in the order confirmation of the supplier apply.

Ambient conditions

The ambient conditions for the transport and storage of the device correspond to the ambient conditions for operation of the device.
Adhere to the device data sheet!

Returning devices

For the return of devices, follow the instructions in **Repair** on page 44.

6 Installation

Safety instructions

⚠ CAUTION

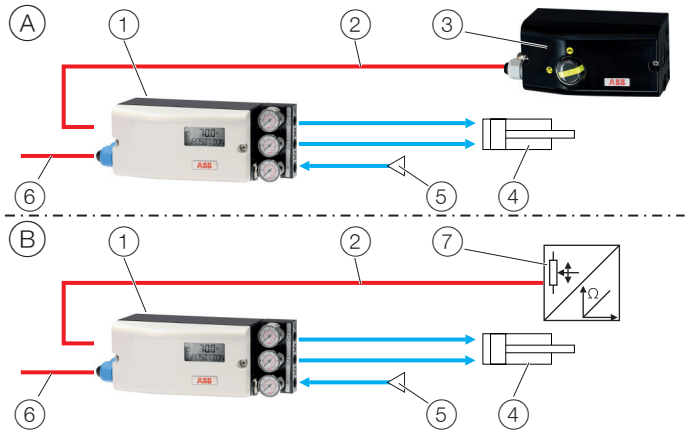
Risk of injury due to incorrect parameter values!
Incorrect parameter values can cause the valve to move unexpectedly. This can lead to process failures and result in injuries.

- Before recommissioning a positioner that was previously in use at another location, always reset the device to its factory settings.
- Never start automatic adjustment before restoring the factory settings!

Note
Before assembly, check whether the positioner meets the control and safety requirements for the installation location (actuator or final control element).
Refer to the **Specification** in the data sheet.

Only qualified specialists who have been trained for these tasks are authorized to mount and adjust the unit, and to make the electrical connection.
When carrying out any work on the device, always observe the local accident prevention regulations and the regulations concerning the construction of technical installations.

External position sensors



1 TZIDC Control Unit
2 Connection cable
3 TZIDC Remote Sensor
4 Actuator
5 Compressed air supply
6 Set point signal
7 Remote position sensor

Figure 4: TZIDC with external position sensors

Note
If the device is being operated on a cylinder, for reasons associated with linearity you should run automatic adjustment for rotary actuators (refer to **Standard automatic adjustment for rotary actuators** on page 31).

(A) TZIDC Control Unit with TZIDC Remote Sensor*
In this version, the components are supplied in two housings, which together form one harmonized unit.
The following points should be observed during installation:

- Housing 1 (TZIDC Control Unit) contains the electronics and pneumatics and is mounted separately from the actuator.
- Housing 2 (TZIDC Remote Sensor) contains the position sensor and is mounted on the linear and rotary actuator. Perform mechanical mounting as described in **Mechanical mounting** on page 16.
- The electrical connection is performed as described in **Connection on device – TZIDC Control Unit for remote position sensor** on page 28.

Note
To connect the TZIDC Remote Sensor, a cable with the following specifications needs to be used:

- 3-wire, cross-section 0.5 to 1.0 mm^2
- shielded, with at least 85 % coverage
- Temperature range up to at least 100 °C (212 °F)

The cable glands must also be approved for a temperature range up to at least 100 °C (212 °F). The cable glands require a mounting for the shielding and strain relief for the cable in addition.
ABB optionally offers a cable gland and cable for the TZIDC Remote Version.

* The TZIDC Remote Version is temporarily not available for the marine version.

(B) TZIDC Control Unit for remote position sensor
In this version the positioner is supplied without a position sensor.
The following points should be observed during installation:

- Housing 1 (TZIDC Control Unit) contains the electronics and pneumatics and is mounted separately from the actuator.
- The remote position sensor is mounted on the linear and rotary actuator. Follow the operating instructions for the remote position sensor for mechanical mounting!
- The electrical connection is performed as described in **Connection on device – TZIDC Control Unit for remote position sensor** on page 28.

… 6 Installation

Mechanical mounting

General

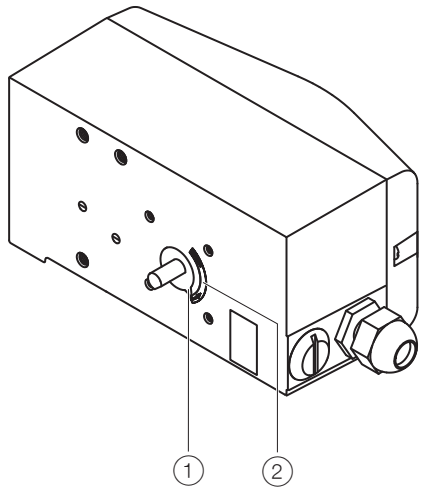
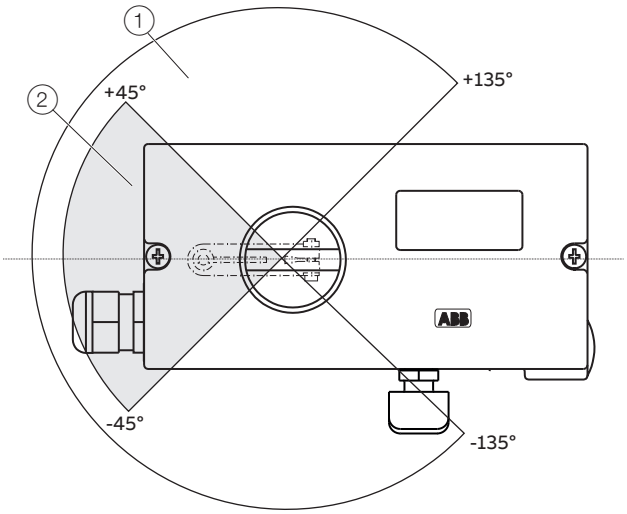


Figure 5: Operating range

Arrow (1) on the device feedback shaft (position feedback point) must move between the arrow marks (2).



(1) Measuring range (2) Operating range

Figure 6: Measuring and operating ranges of the positioner

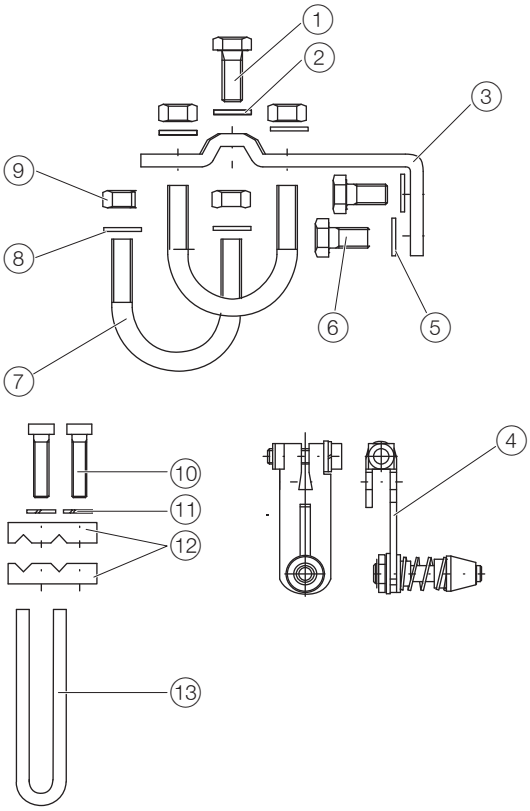
Operating range for linear actuators:
The operating range for linear actuators is ±45° symmetrically to the longitudinal axis. The usable span within the operating range is at least 25° (recommended figure 40°). The usable span does not necessarily need to run symmetrically to the longitudinal axis.

Operating range of rotary actuators:
The usable span is 90°, which must be entirely within the measuring range, but does not necessarily need to run symmetrically to the longitudinal axis.

Note
During installation make sure that the actuator travel or rotation angle for position feedback is implemented correctly.

Mounting on linear actuators

For mounting on a linear actuator in accordance with DIN / IEC 534 (lateral mounting as per NAMUR), the following attachment kit is available:



1. Screw
2. Washer
3. Mounting bracket
4. Lever with follower pin (for mechanical stroke 10 to 35 mm [0.39 to 1.38 in] or 20 to 100 mm [0.79 to 3.94 in])
5. Washers
6. Screws
7. U-bolts
8. Washers
9. Nuts
10. Screws
11. Spring washers
12. Clamp plates
13. Follower guide

Figure 7: Attachment kit

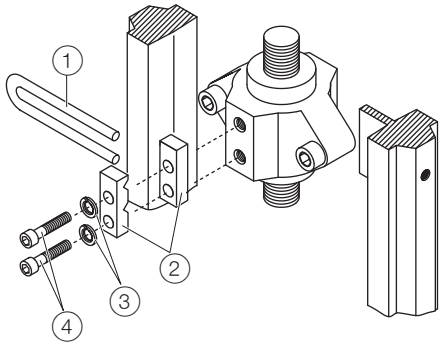


Figure 8: Attaching a follower guide to the actuator

1. Tighten the screws so that they are hand-tight.
2. Attach the follower guide (1) and clamp plates (2) with screws (4) and spring washers (3) to the actuator stem.

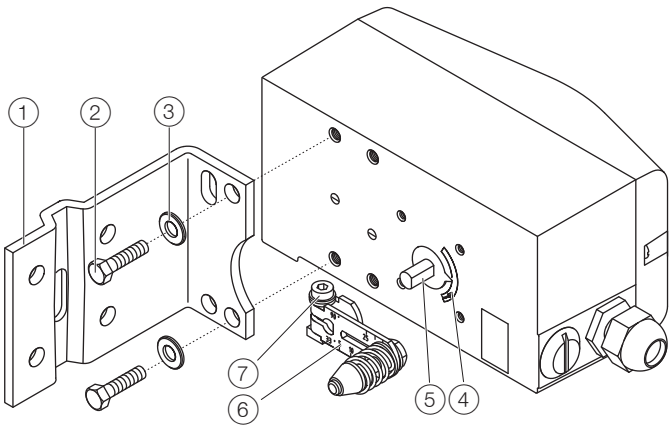


Figure 9: Mounting lever and bracket on the positioner

1. Attach the lever (6) to the feedback shaft (5) of the positioner (can only be mounted in one position due to the cut shape of the feedback shaft).
2. Using the arrow marks (4), check whether the lever moves within the operating range (between the arrows).
3. Hand-tighten the screw (7) on the lever.

… 6 Installation

… Mechanical mounting

4. Hold the prepared positioner (with the mount bracket ① still loose) on the actuator so that the follower pin for the lever enters the follower guide to determine which tap holes on the positioner must be used for the mount bracket.
5. Secure the mount bracket ① with screws ② and washers ③ using the relevant tap holes on the positioner housing. Tighten the screws as evenly as possible to ensure subsequent linearity. Align the mount bracket in the oblong hole to ensure that the operating range is symmetrical (lever moves between the arrow marks ④).

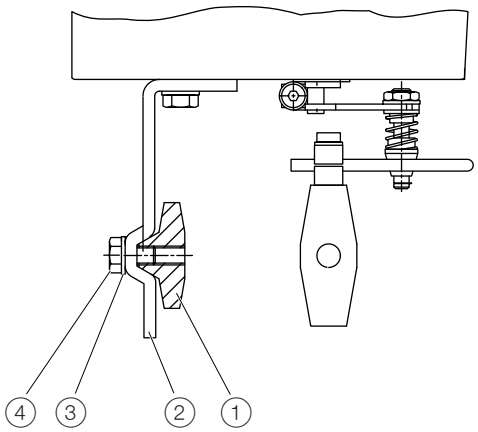


Figure 10: Mounting on a cast iron yoke

1. Attach the mount bracket ② with screw ④ and washer ③ to the cast iron yoke ①.

or

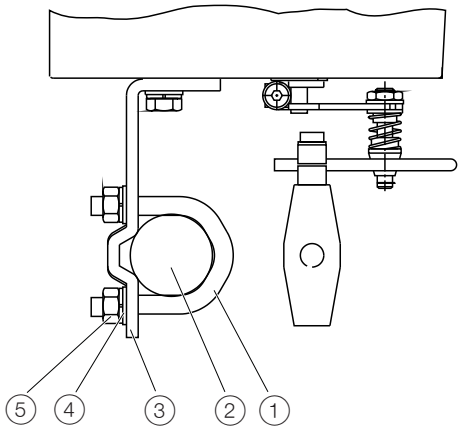
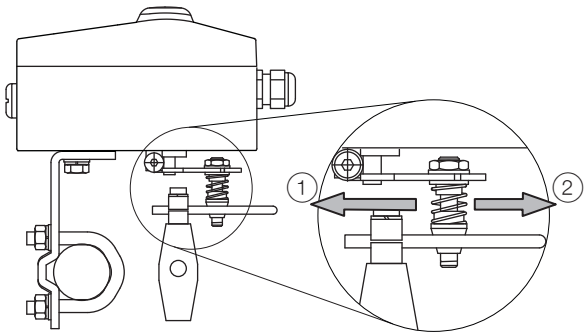


Figure 11: Mounting on a columnar yoke

1. Hold the mount bracket ③ in the proper position on the columnar yoke ②.
2. Insert the U-bolts ① from the inside of the columnar yoke ② through the holes of the mount bracket.
3. Add the washers ④ and nuts ⑤.
4. Tighten the nuts so that they are hand-tight.

Note
Adjust the height of the positioner on the cast iron yoke or columnar yoke until the lever is horizontal (based on a visual check) at half stroke of the valve.



① Increase linkage ② Decrease linkage

Figure 12: Positioner linkage

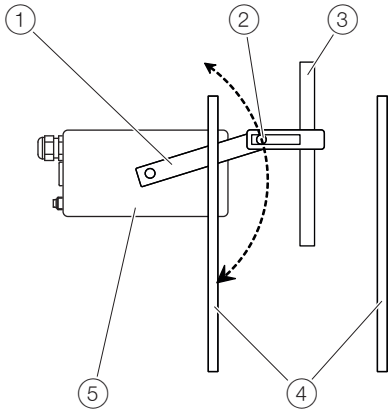
The scale on the lever indicates the link points for the various stroke ranges of the valve.
Move the bolt with the follower pin in the oblong hole of the lever to adjust the stroke range of the valve to the working range for the position sensor.
Moving the link point inwards increases the rotation angle of the sensor. Moving the link point outwards reduces the rotation angle of the sensor.
Adjust the actuator stroke to make use of as large an angle of rotation as possible (symmetrical around the center position) on the position sensor.

Recommended range for linear actuators:
- –28 to 28°

Minimum angle:
- 25°

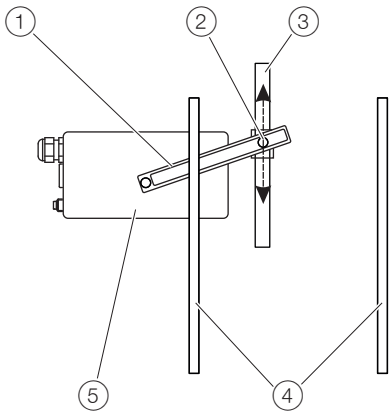
Note
After mounting, check whether the positioner is operating within the measuring range.

Position of actuator bolt
The actuator bolt for moving the potentiometer lever can be mounted permanently on the lever itself or on the valve stem. Depending on the mounting method, when the valve moves the actuator bolt performs either a circular or a linear movement with reference to the center of rotation of the potentiometer lever. Select the chosen bolt position in the HMI menu in order to ensure optimum linearization. The default setting is actuator bolt on lever.



① Potentiometer lever ④ Valve yoke
② Actuator bolts ⑤ Positioner
③ Valve stem

Figure 13: Actuator bolts on the lever (rear view)



① Potentiometer lever ④ Valve yoke
② Actuator bolts ⑤ Positioner
③ Valve stem

Figure 14: Actuator bolts on the valve (rear view)

… 6 Installation

… Mechanical mounting

Mounting on rotary actuator

For mounting on part-turn actuators in accordance with VDI / VDE 3845, the following attachment kit is available:

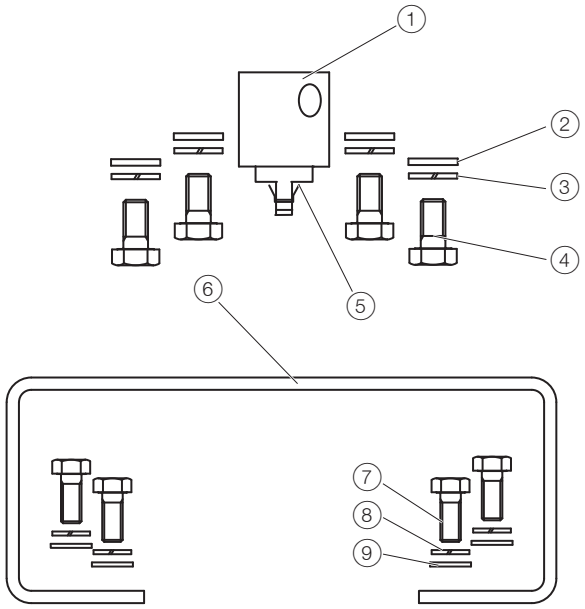


Figure 15: Components of attachment kit

- Adapter (1) with spring (5)
- four M6 screws each (4), spring washers (3) and washers (2) to fasten the attachment bracket (6) to the positioner
- four M5 screws (7), Spring washers (8) and washers (9) to fasten the attachment bracket to the actuator

Required tools:

- Wrench, size 8 / 10
- Allen key, size 3

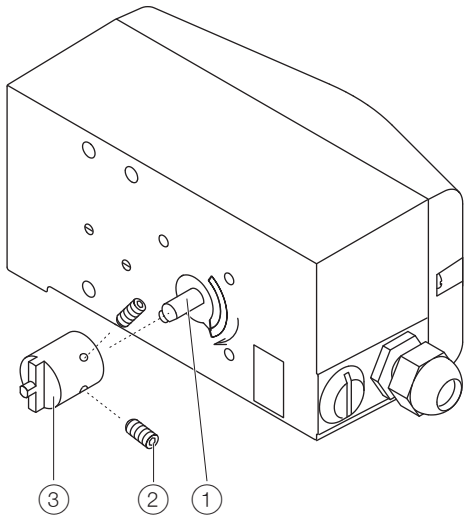
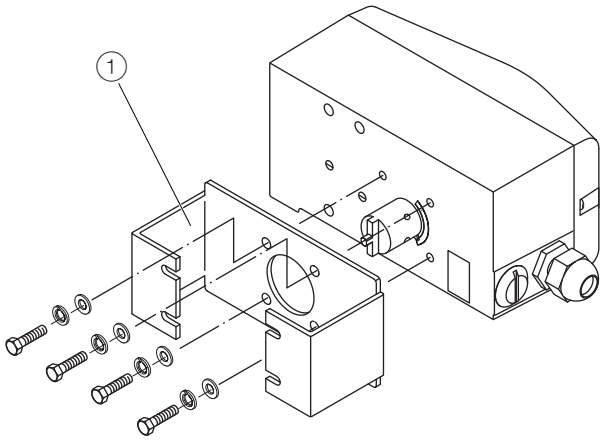


Figure 16: Mounting the adapter on the positioner

1. Determine the mounting position (parallel to actuator or at 90° angle)
2. Calculate the rotational direction of the actuator (right or left).
3. Move the part-turn actuator into the home position.
4. Pre-adjust feedback shaft.
   To make sure that the positioner runs within the operating range (refer to **General** on page 16), the mounting position as well as the basic position and rotation direction of the actuator must be considered when determining the adapter position on axis (1). For this purpose, the feedback shaft can be adjusted manually so that the adapter (3) can be attached in the correct position.
5. Place the adapter in the proper position on the feedback shaft and fasten with threaded pins (2). One of the threaded pins must be locked in place on the flat side of the feedback shaft.



① Attachment bracket

Figure 17: Screwing the attachment bracket onto the positioner

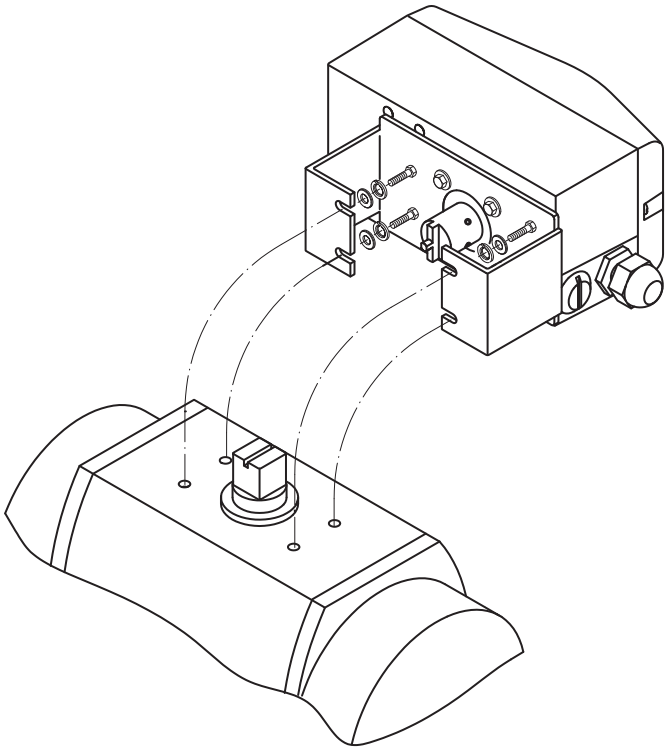


Figure 18: Screwing the positioner onto the actuator

Note
After mounting, check whether the operating range of the actuator matches the measuring range of the positioner, refer to **General** on page 16.

Electrical connections

⚠ DANGER

Risk of explosion for devices with local communication interface (LCI)
A local communication interface (LCI) may not be operated in hazardous areas.
- Never use the local communication interface (LCI) on the main board in a hazardous area!

⚠ WARNING

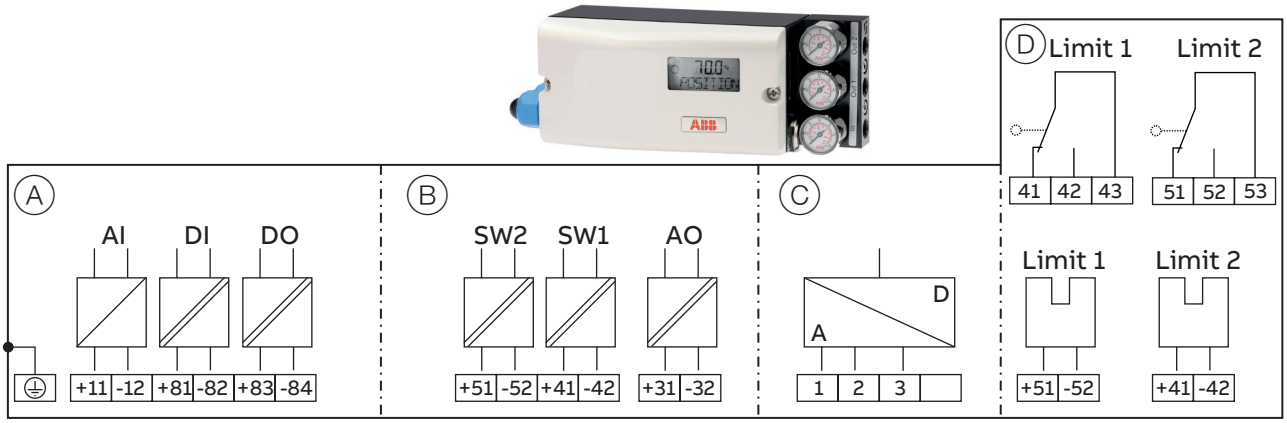
Risk of injury due to live parts!
When the housing is open, contact protection is not provided and EMC protection is limited.
- Before opening the housing, switch off the power supply.

The electrical connection may only be established by authorized specialist personnel.
Notices on electrical connection in this instruction must be observed; otherwise, electric safety and the IP-rating may be adversely affected.
Safe isolation of electric circuits which are dangerous if touched is only guaranteed when the connected devices fulfill the requirements of EN 61140 (basic requirements for secure separation).
To ensure safe isolation, install supply lines so that they are separate from electrical circuits which are dangerous if touched, or implement additional isolation measures for them.

… 6 Installation

… Electrical connections

Positioner / TZIDC Control Unit Electrical Connection



(A) Basic device

(B) Options

(C) Connection TZIDC Remote Sensor / remote position sensor (only for TZIDC Control Unit version)

(D) Options, limit value monitor with proximity switches or microswitches (not for TZIDC Control Unit version)

Figure 19: TZIDC Electrical connection

Connections for inputs and outputs

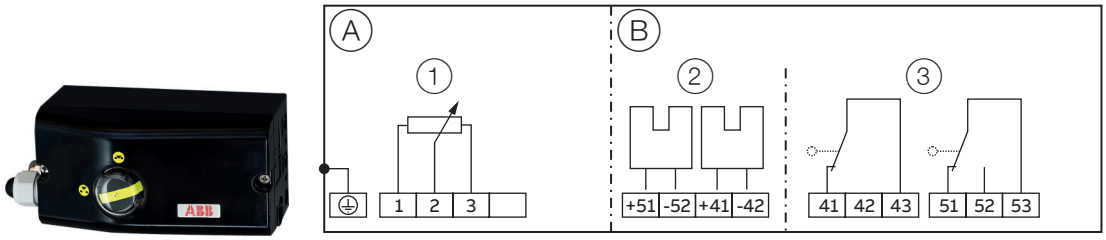
Terminal	Function / comments
+11 / −12	**Analog input**
+81 / −82	**Binary input DI**
+83 / −84	**Binary output DO2**
+51 / −52	**Digital feedback SW1** (Option module)
+41 / −42	**Digital feedback SW2** (Option module)
+31 / −32	**Analog feedback AO** (Option module)
1 / 2 / 3	**TZIDC remote sensor** (Only for options TZIDC Remote Sensor or TZIDC for remote position sensor)

Terminal	Function / comments
+51 / −52	**Limit switch Limit 1 with proximity switch** (optional)
+41 / −42	**Limit switch Limit 2 with proximity switch** (optional)
41 / 42 / 43	**Limit switch Limit 1 with microswitch** (optional)
51 / 52 / 53	**Limit switch Limit 2 with microswitch** (optional)

Note

The TZIDC can be fitted either with proximity switches or microswitches as limit switches. It is not possible to combine both variants. For the version TZIDC Control Unit with TZIDC Remote Sensor, the limit switches are located in the TZIDC Remote Sensor.

TZIDC Remote Sensor Electrical Connection



(A) Basic device
(B) Options
(1) Position sensor
(2) Limit monitor with proximity switches (optional)
(3) Limit monitor with microswitches (optional)

Figure 20: TZIDC Remote Sensor Electrical Connection

Connections for inputs and outputs

Terminal	Function / comments
1 / 2 / 3	**TZIDC control unit**
+51 / –52	**Proximity switches Limit 1** (Option)
+41 / –42	**Proximity switches Limit 2** (Option)
41 / 42 / 43	**Microswitches Limit 1** (Option)
51 / 52 / 53	**Microswitches Limit 2** (Option)

Note
The TZIDC Remote Sensor can be fitted either with proximity switches or microswitches as limit switches. It is not possible to combine both variants.

Electrical data for inputs and outputs

Note
When using the device in potentially explosive atmospheres, note the additional connection data in **Use in potentially explosive atmospheres** on page 5!

Analog input

Set point signal analog (two-wire technology)	
Terminals	+11 / –12
Nominal operating range	4 to 20 mA
Split range configuration between	20 to 100 % of the nominal operating range can be parameterized
Maximum	50 mA
Minimum	3.6 mA
Starting at	3.8 mA
Load voltage	9.7 V at 20 mA
Impedance at 20 mA	485 Ω

… 6 Installation

… Electrical connections

Digital input

Input for the following functions:

- no function
- move to 0 %
- move to 100 %
- Hold previous position
- block local configuration
- block local configuration and operation
- block any access (local or via PC)

Binary input DI	
Terminals	+81 / −82
Supply voltage	24 V DC (12 to 30 V DC)
Input ‘logical 0’	0 to 5 V DC
Input ‘logical 1’	11 to 30 V DC
Input Current	Maximum 4 mA

Binary output

Output configurable as alarm output by software.

Binary output DO	
Terminals	+83 / −84
Supply voltage	5 to 11 V DC (Control circuit in accordance with DIN 19234/NAMUR)
Output ‘logical 0’	> 0.35 mA to < 1.2 mA
Output ‘logical 1’	> 2.1 mA
Direction of action	Configurable ‘logical 0’ or ‘logical 1’

Option modules

Module for analog feedback AO*

Without any signal from the positioner (e.g. ‘no power’ or ‘initializing’) the module sets the output to > 20 mA (alarm level).

Terminals	+31 / −32
Signal range	4 to 20 mA (split ranges can be parameterized)
• in the event of an error	> 20 mA (alarm level)
Supply voltage, two-wire technology	24 V DC (11 to 30 V DC)
Characteristic curve	rising or falling (configurable)
Deviation	< 1 %

Module for digital feedback SW1, SW2*

Terminals	+41 / −42, +51 / −52
Supply voltage	5 to 11 V DC (Control circuit in accordance with DIN 19234 / NAMUR)
Output ‘logical 0’	< 1.2 mA
Output ‘logical 1’	> 2.1 mA
Direction of action	Configurable ‘logical 0’ or ‘logical 1’
Description	2 software switches for binary position feedback (position adjustable within the range of 0 to 100 %, ranges cannot overlap)

* The module for analog feedback and the module for digital feedback have separate slots and can be used together.

Assembly kits for limit monitor

Two proximity switches or microswitches for independent signaling of the actuator position, switching points are adjustable between 0 to 100%

Limit monitor with proximity switches Limit 1, Limit 2

Terminals	+41 / −42, +51 / −52	
Supply voltage	5 to 11 V DC (Control circuit in accordance with DIN 19234/NAMUR)	
Direction of action	Metal tag in proximity switch	Metal tag outside proximity switch
Type SJ2-SN (NC; log 1)	< 1.2 mA	> 2.1 mA

Limit monitor with 24 V microswitches Limit 1, Limit 2

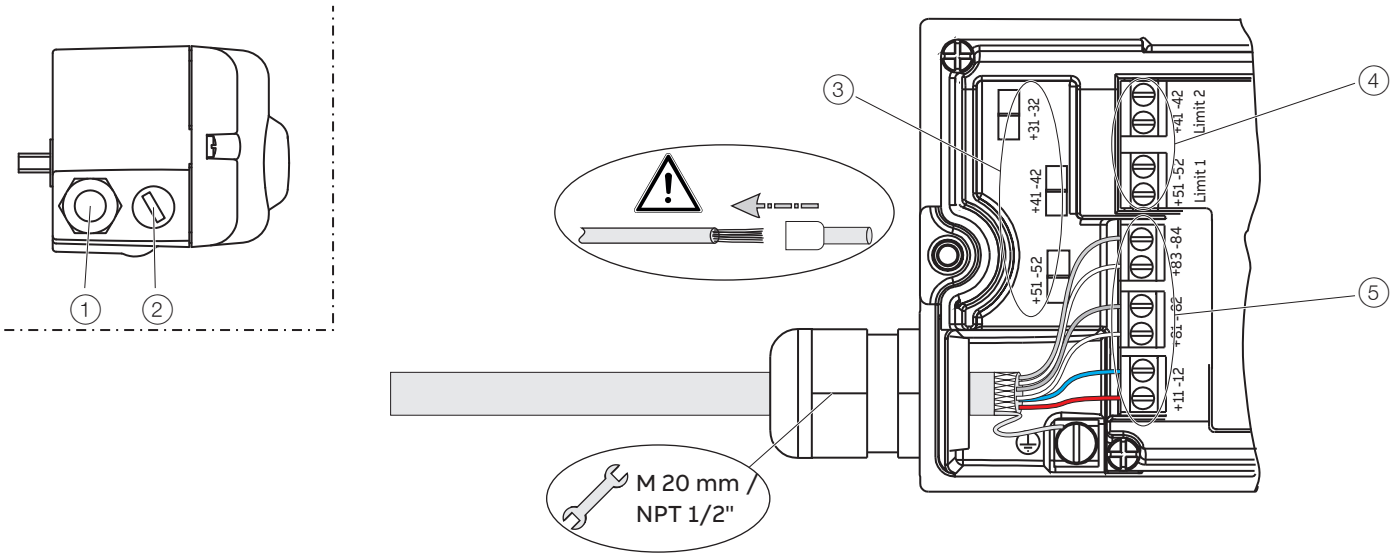
Terminals	+41 / −42, +51 / −52
Supply voltage	maximum 24 V AC/DC
Load rating	Maximum 2 A
Contact surface	10 µm Gold (AU)

Mechanical position indicator

Indicator disk in enclosure cover linked with device feedback shaft.

These options are also available for retrofitting by Service.

Connection on the device



1. Cable gland
2. Blind plug
3. Terminals for option modules
4. Terminal attachment kit for digital feedback
5. Terminals for basic unit

Figure 21: Connection to device (example)

2 tap holes ½- 14 NPT or M20 × 1.5 are provided on the left side of the housing for cable entry in the housing. One of the tap holes is fitted with a cable gland, while the other tap hole has a blind plug.

Note
The connecting terminals are delivered closed and must be unscrewed before inserting the wire.

1. Strip the wires to approximately 6 mm (0.24 in).
2. Connect the wires to the connecting terminals in line with the connection diagram.

… 6 Installation

… Electrical connections

Wire cross-sectional areas

Basic device

Electrical connections	
4 to 20 mA input	Screw terminals max. 2.5 mm^2 (AWG14)
Options	Screw terminals max. 1.0 mm^2 (AWG18)

Cross section	
Rigid / flexible wires	0.14 to 2.5 mm^2 (AWG26 to AWG14)
Flexible with wire end sleeve	0.25 to 2.5 mm^2 (AWG23 to AWG14)
Flexible with wire end sleeve no plastic sleeve	0.25 to 1.5 mm^2 (AWG23 to AWG17)
Flexible with wire end sleeve with plastic sleeve	0.14 to 0.75 mm^2 (AWG26 to AWG20)

Multi-wire connection capacity (two wire with the same cross-section)	
Rigid / flexible wires	0.14 to 0.75 mm^2 (AWG26 to AWG20)
Flexible with wire end sleeve no plastic sleeve	0.25 to 0.75 mm^2 (AWG23 to AWG20)
Flexible with wire end sleeve with plastic sleeve	0.5 to 1.5 mm^2 (AWG21 to AWG17)

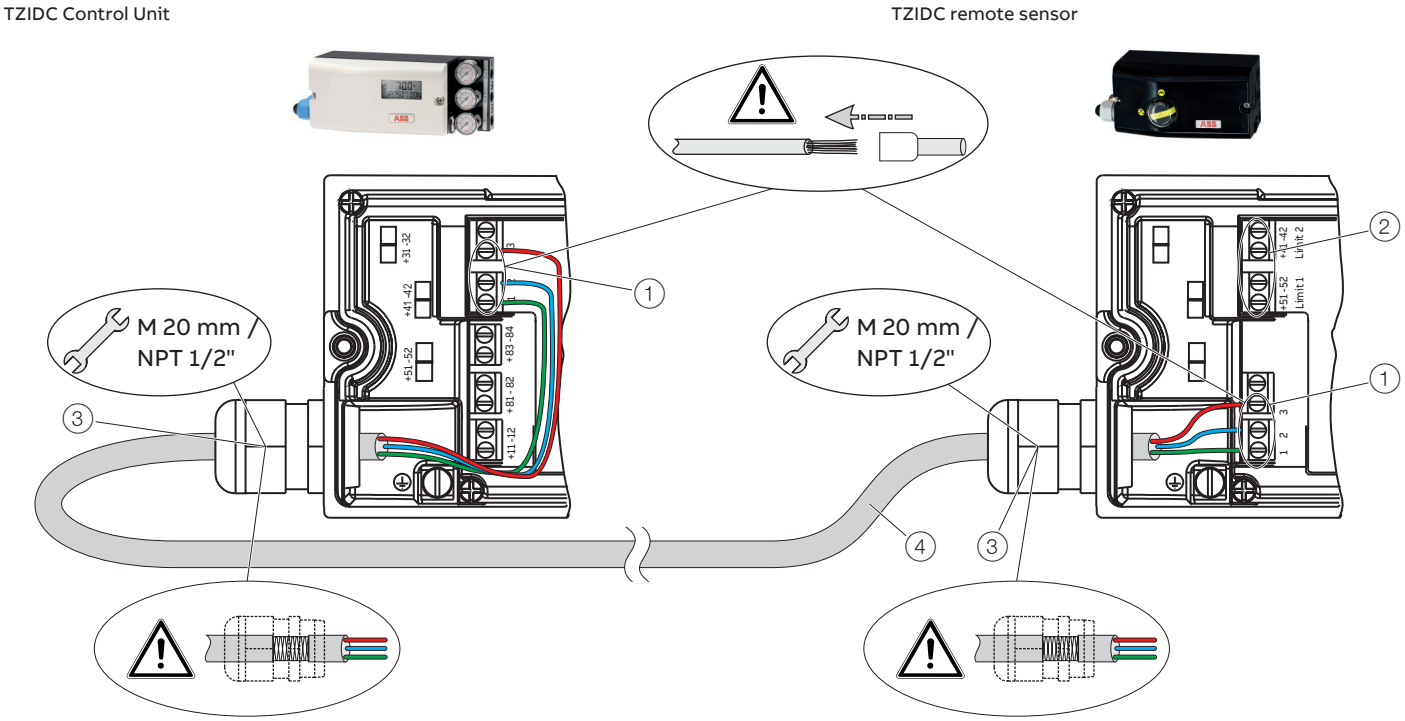
Option modules

Cross section	
Rigid / flexible wires	0.14 to 1.5 mm^2 (AWG26 to AWG17)
Flexible with wire end sleeve no plastic sleeve	0.25 to 1.5 mm^2 (AWG23 to AWG17)
Flexible with wire end sleeve with plastic sleeve	0.25 to 1.5 mm^2 (AWG23 to AWG17)

Multi-wire connection capacity (two wire with the same cross-section)	
Rigid / flexible wires	0.14 to 0.75 mm^2 (AWG26 to AWG20)
Flexible with wire end sleeve no plastic sleeve	0.25 to 0.5 mm^2 (AWG23 to AWG22)
Flexible with wire end sleeve with plastic sleeve	0.5 to 1 mm^2 (AWG21 to AWG18)

Limit switch with proximity switches or 24 V microswitches	
Rigid wire	0.14 to 1.5 mm^2 (AWG26 to AWG17)
Flexible wire	0.14 to 1.0 mm^2 (AWG26 to AWG18)
Flexible with wire end sleeve no plastic sleeve	0.25 to 0.5 mm^2 (AWG23 to AWG22)
Flexible with wire end sleeve with plastic sleeve	0.25 to 0.5 mm^2 (AWG23 to AWG22)

Connection on device - TZIDC Control Unit with TZIDC Remote Sensor



① Terminals TZIDC Remote Sensor
② Terminal attachment kit for digital feedback
③ EMC Cable gland
④ Shielded connection cable

Figure 22: Connection of TZIDC Control Unit with TZIDC Remote Sensor (example)

In the case of the 'TZIDC Control Unit with TZIDC Remote Sensor' design, the components are supplied in two housings, which together form one harmonized unit.
Housing 1 (TZIDC Control Unit) contains the electronics and pneumatics along with the following options (where applicable):

- Analog position feedback
- Digital position feedback

Housing 2 (TZIDC Remote Sensor) contains the position sensor and is suitable for mounting on linear or part-turn actuators.
If necessary, the following options can be installed if required:

- Optical position indicator
- Mechanical feedback contacts designed as proximity switches or microswitches.

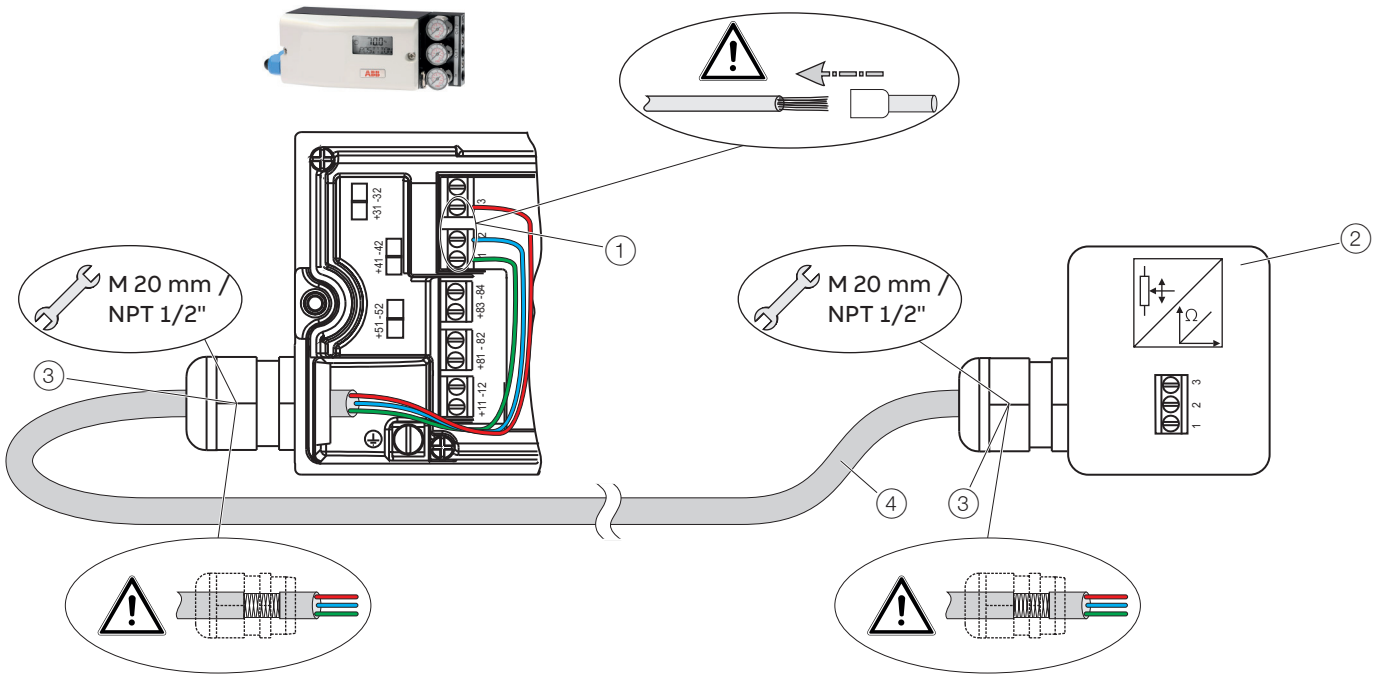
Connect the positioner (TZIDC Control Unit, housing 1) and remote position sensor (TZIDC Remote Sensor, housing 2) while following the instructions below:

- The sensor and the electronics have been matched. Ensure that only devices with the same serial number are connected.
- A shielded 3-wire cable with a maximum length of 10 m (33 ft) must be used for the connection.
- Route the cable into the terminal compartment through the EMC cable glands. Ensure that the shielding is secured correctly in the EMC cable glands.
- Connect the cables in accordance with the electrical connections and tighten the screws of the terminals so that they are hand-tight.
- The electrical connection of the TZIDC Control Unit and the optional modules are described in **Positioner / TZIDC Control Unit Electrical Connection** on page 22.
- If the TZIDC Control Unit is fastened so that it is it non-conductive, the housing must be grounded (TZIDC Control Unit and TZIDC Remote Sensor housing with the same electric potential); otherwise control deviations could occur with regard to analog position feedback.
- Use wire end ferrules when connecting.

… 6 Installation

… Electrical connections

Connection on device – TZIDC Control Unit for remote position sensor



1. Terminals for remote position sensor
2. Remote position sensor
3. EMC Cable gland
4. Shielded connection cable

Figure 23: Connection of TZIDC Control Unit with remote position sensor (example)

With the TZIDC designed for remote position sensors, the positioner is supplied without a position sensor.

The TZIDC Control Unit contains the electronics and pneumatics along with the following options (where applicable):

- Analog position feedback
- Digital position feedback

Any position sensor (4 to 30 kΩ, with line break detection 4 to 18 kΩ) can be connected.

Connect the positioner (TZIDC Control Unit) and remote position sensor while observing the following instructions:

- A shielded 3-wire cable with a maximum length of 10 m (33 ft) must be used for the connection.
- Route the cable into the terminal compartment through the EMC cable glands. Ensure that the shielding is secured correctly in the EMC cable glands.
- Connect the cables in accordance with the electrical connections and tighten the screws of the terminals so that they are hand-tight.
- The electrical connection of the TZIDC Control Unit and the optional modules are described in **Positioner / TZIDC Control Unit Electrical Connection** on page 22.
- If the TZIDC Control Unit is fastened such that it is it non-conductive, the housing must be grounded (TZIDC Control Unit and remote position sensor housing with the same electric potential); otherwise control deviations could occur with regard to analog position feedback.
- Use wire end ferrules when connecting.

Pneumatic connections

Note

The positioner must only be supplied with instrument air that is free of oil, water, and dust.

The purity and oil content must meet the requirements of Class 3 in accordance with DIN/ISO 8573-1.

NOTICE

Damage to components!

Contamination on the air pipe and positioner can damage components.

- Dust, splinters, and any other particles of dirt must be blown-out before the pipe is connected.

NOTICE

Damage to components!

Pressure above 6 bar (90 psi) can damage the positioner or actuator.

- Provisions must be made (e.g., by using a pressure reducer) to make sure that the pressure does not rise above 6 bar (90 psi)*, even in the event of a fault.

* 5.5 bar (80 psi) (marine version)

Information on double acting actuators with spring-return mechanism

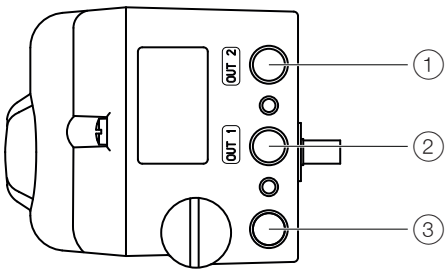
On double-acting actuators with spring-return mechanism, a pressure that significantly exceeds the supply air pressure value can be generated during operation by the springs in the chamber opposite the springs.

This may damage the positioner or adversely affect control of the actuator.

To eliminate the possibility of this occurring, it is recommended to install a pressure compensation valve between the springless chamber and the supply air for these types of applications. It enables the increased pressure to be transferred back to the air inlet line.

The opening pressure of the check valve should be < 250 mbar (< 3.6 psi).

Connection on the device



① OUT 2
② OUT 1
③ IN

Figure 24: Pneumatic connections

Marking	Pipe connection
IN	Supply air, pressure 1.4 to 6 bar (20 to 90 psi) Marine version: • Supply air, pressure 1.4 to 5.5 bar (20 to 80 psi)**
OUT1	Output pressure to the actuator
OUT2	Output pressure to the actuator (2. Connection with double acting actuator)

** (marine version)

Join the pipe connections according to the designation, observing the following points:

- All pneumatic piping connections are located on the right-hand side of the positioner. G¼ or ¼ 18 NPT tap holes are provided for the pneumatic connections. The positioner is labeled according to the tap holes available.
- We recommend that you use a pipe with dimensions of 12 × 1.75 mm.
- The supply air pressure required to apply the actuating force must be adjusted in line with the output pressure in the actuator. The operating range of the positioner is between 1.4 to 6 bar (20 to 90 psi)***.

*** 1.4 to 5.5 bar (20 to 80 psi) marine version

… 6 Installation

… Pneumatic connections

Air supply

Instrument air*	
Purity	Maximum particle size: 5 µm Maximum particle density: 5 mg/m³
Oil content	Maximum concentration 1 mg/m³
Pressure dew point	10 K below operating temperature
Supply pressure**	Standard design: 1.4 to 6 bar (20 to 90 psi) Marine version: 1.6 to 5.5 bar (23 to 80 psi)
Air consumption***	< 0.03 kg/h / 0.015 scfm

* Free of oil, water and dust in accordance with DIN / ISO 8573-1. Pollution and oil content in accordance with Class 3

** Do not exceed the maximum output pressure of the actuator

*** Independent of supply pressure

7 Commissioning

Note
The electrical power supply and supply air pressure data indicated on the name plate must be complied with during commissioning.

⚠ CAUTION

Risk of injury due to incorrect parameter values!
Incorrect parameter values can cause the valve to move unexpectedly. This can lead to process failures and result in injuries.

- Before recommissioning a positioner that was previously in use at another location, always reset the device to its factory settings.
- Never start automatic adjustment before restoring the factory settings!

Note
Please observe the information in **Operation** on page 34 to operate the device!

Commissioning the positioner:

1. Open the pneumatic power supply.
2. Power-up the electric power supply and feed in the setpoint signal 4 to 20 mA.
3. Checking mechanical mounting:
   - Press and hold **MODE**; in addition, press ⬆ or ⬇ until operating mode 1.3 (manual adjustment in the measuring range) is displayed. Release **MODE**.
   - Press⬆ or ⬇ to move the actuator into the mechanical end position; check the end positions; rotational angle is displayed in degrees; for high-speed mode, press ⬆ or ⬇ simultaneously.

Recommended rotational angle range	
Linear actuators	–28 to 28°
Rotary actuators	–57 to 57°
Minimum angle	25°

4. Perform standard automatic adjustment in accordance with **Standard automatic adjustment** on page 31.

Commissioning of the positioner is now complete, and the device is ready for operation.

Operating modes

Selection from the operating level

1. Press and hold down **MODE**.
2. Also press and release ⬆ rapidly as often as required. The selected operating mode is displayed.
3. Release **MODE**.

The position is displayed in % or as a rotation angle.

Operating mode	Mode indicator	Position indicator
1.0 Control mode* with adaptation of the control parameters		
1.1 Control mode* without adaptation of the control parameters		
1.2 Manual adjustment** in the operating range. Adjust*** using ⬆ or ⬇		
1.3 Manual adjustment** in the measuring range. Adjust*** using ⬆ or ⬇		 M10906h

* Since self-optimization in operating mode 1.0 is subject to several factors during control operation with adaptation, incorrect adjustments could appear over an extended period.

** Positioning not active.

*** For high-speed mode, press ⬆ and ⬇ simultaneously.

Standard automatic adjustment

Note

Standard Auto Adjust does not always result in optimum control conditions.

Standard automatic adjustment for linear actuators*

1. **MODE** Press and hold until **ADJ_LIN** is displayed.
2. **MODE** Press and hold until the countdown ends.
3. Release **MODE**; this starts Autoadjust.

Standard automatic adjustment for rotary actuators*

1. **ENTER** Press and hold until ADJ_ROT is displayed.
2. **ENTER** Press and hold until the countdown ends.
3. Release **ENTER**; this starts Autoadjust.

If Autoadjust is successful, the parameters will be stored automatically and the positioner will revert to operating mode 1.1.

If an error occurs during Autoadjust, the process will be terminated with an error message.

Perform the following steps if an error occurs:

1. Press and hold down operating button ⬆ or ⬇ for approximately three seconds.

The unit will switch to the operating level, mode 1.3 (manual adjustment within the measuring range).

2. Check mechanical mounting in accordance with **Mechanical mounting** on page 16 and repeat the standard automatic adjustment.

* The zero position is determined automatically and saved during standard automatic adjustment, counter-clockwise (CTCLOCKW) for linear actuators and clockwise (CLOCKW) for rotary actuators.

… 7 Commissioning

Sample parameters

'Change the zero position of the LCD display from clockwise (CLOCKW) to counter-clockwise limit stop (CTCLOCKW)'

Initial situation: the positioner is in bus operation on the operating level.

1. Switching to the configuration level:
   - Press and hold down🡅 and 🡇 simultaneously,
   - additionally quickly press and release **ENTER**,
   - Wait for the countdown to go from 3 to 0,
   - Release🡅 and 🡇.

   The following is now shown in the display:

2. Switching to parameter group 3._:
   - Press and hold down**MODE** and **ENTER** simultaneously,
   - additionally quickly press and release 🡅 2×,

   The following is now shown in the display:

   - Release**MODE** and **ENTER** .

   The following is now shown in the display:

3. Selecting parameter 3.2:
   - Press and hold down**MODE**,
   - additionally quickly press and release 🡅 2×,

   The following is now shown in the display:

   — Release **MODE**.

4. Changing parameter settings:
   - Quickly press and release 🡅 to select **CTCLOCKW**.

5. Switching to parameter 3.3 (Return to operating level) and saving the new settings:
   - Press and hold down**MODE**,
   - additionally quickly press and release 🡅 2×,

   The following is now shown in the display:

   - Release**MODE**,
   - Quickly press and release 🡅 to select **NV_SAVE**,
   - Press**ENTER** and hold down until the countdown goes from 3 to 0.

The new parameter setting is saved and the positioner automatically returns to the operating level. It continues in the operating mode that was active prior to the configuration level being called up.

Setting the option modules

Setting the mechanical position indication

1. Loosen the screws for the housing cover and remove it.
2. Rotate the position indicator on the shaft to the desired position.
3. Attach the housing cover and screw it onto the housing. Tighten the screws so that they are hand-tight.
4. Attach the symbol label to mark the minimum and maximum valve positions on the housing cover.

Note
The labels are located on the inside of the housing cover.

Setting the mechanical limit switch with proximity switches

1. Loosen the screws for the housing cover and remove it.

⚠ CAUTION

Risk of injury!

The device includes slot sensors with sharp edges.

- Adjust the metal tags using a screwdriver only!

2. Set the upper and lower switching points for binary feedback as follows:
   - Select the 'Manual Adjustment' operating mode and move the final control element by hand into the lower switching position.
   - Using a screwdriver, adjust the metal tag of proximity switch 1 (lower contact) on the axis until contact is made, i. e., just before it is inserted in the proximity switch. The slot sensor enters proximity switch 1 when the feedback shaft is rotated clockwise (as viewed from the front).
   - Move the final control element by hand into the upper switching position.
   - Using a screwdriver, adjust the metal tag of proximity switch 2 (upper contact) on the axis until contact is made, i. e., just before it is inserted in the proximity switch. The slot sensor enters proximity switch 2 when the feedback shaft is rotated counter-clockwise (as viewed from the front).
3. Attach the housing cover and screw it onto the housing.
4. Tighten the screws so that they are hand-tight.

Setting the mechanical limit switch with 24 V microswitches

1. Loosen the screws for the housing cover and remove it.
2. Select the 'Manual Adjustment' operating mode and move the final control element by hand into the desired switching position for contact 1.
3. Set maximum contact (①, lower washer).
   Fasten the upper washer with the special adjustment retainer and rotate the lower washer manually.
4. Select the 'Manual Adjustment' operating mode and move the final control element by hand into the desired switching position for contact 2.
5. Set minimum contact (②, upper washer);
   Fasten the lower washer with the special adjustment retainer and rotate the upper washer manually.
6. Connect the microswitch.
7. Attach the housing cover and screw it on to the housing.
8. Tighten the screws so that they are hand-tight.

8 Operation

Safety instructions

⚠ CAUTION

Risk of injury due to incorrect parameter values!

Incorrect parameter values can cause the valve to move unexpectedly. This can lead to process failures and result in injuries.

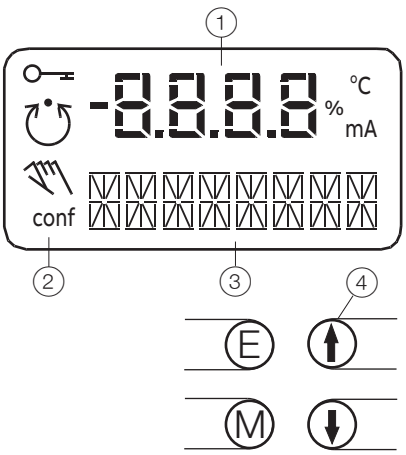
- Before recommissioning a positioner that was previously in use at another location, always reset the device to its factory settings.
- Never start automatic adjustment before restoring the factory settings!

If there is a chance that safe operation is no longer possible, take the device out of operation and secure it against unintended startup.

Parameterization of the device

The LCD display features operating buttons which enable the device to be operated with the housing cover open.

Menu navigation



1. Value display with unit
2. Symbol display
3. Designator display
4. Operating buttons for menu navigation

Figure 25: LCD display with operating buttons

Value display with unit

This 7-segment display with four digits indicates parameter values or parameter reference numbers. For values, the physical unit (°C, %, mA) is also displayed.

Designator display

This 14-segment display with eight digits indicates the designators of the parameters with their status, of the parameter groups, and of the operating modes.

Description of symbols

Symbol	Description
	Operation or access is restricted.
	Control loop is active. The symbol is displayed when the positioner is in operating mode 1.0 CTRL_ADP (adaptive control) or 1.1 CTRL_FIX (fixed control) at operating level. On the configuration level there are test functions for which the controller will be active as well. The control loop symbol will also be displayed when these functions are active.
	Manual adjustment. The symbol is displayed when the positioner is in operating mode 1.2 MANUAL (manual adjustment within the stroke range) or 1.3 MAN_SENS (manual adjustment within the measuring range) at operating level. At configuration level, manual adjustment is active when setting the valve range limits (parameter group 6 MIN_VR (min. of valve range) and 6 MAX_VR (max. of valve range)). The symbol will also be displayed when these parameters are being set.
conf	The configuration icon indicates that the positioner is at the configuration level. The control operation is inactive.

The four operating buttons **ENTER, MODE**, ⬆ and ⬇ are pressed individually or in certain combinations according to the function desired.

Operating button functions

Control button	Meaning
ENTER	• Acknowledge message • Start an action • Save in the non-volatile memory
MODE	• Choose operating mode (operating level) • Select parameter group or parameter (configuration level)
⬆	UP direction button
⬇	DOWN direction button
Press and hold all four buttons for 5 s	Reset

Menu levels

The positioner has two operating levels.

Operating level

On the operating level the positioner operates in one of four possible operating modes (two for automatic control and two for manual mode). Parameters cannot be changed or saved on this level.

Configuration level

On this level most of the parameters of the positioner can be changed locally. The PC is required to change the limit values for the movement counter, the travel counter, and the user-defined characteristic curve.

On the configuration level the active operating mode is deactivated. The I/P module is in neutral position. The control operation is inactive.

NOTICE

Property damage

During external configuration via a PC, the positioner no longer responds to the set point current. This may lead to process failures.

- Before any external parameterization, always move the actuator to the safety position and activate manual adjustment.

… 8 Operation

HART® Parameter Overview

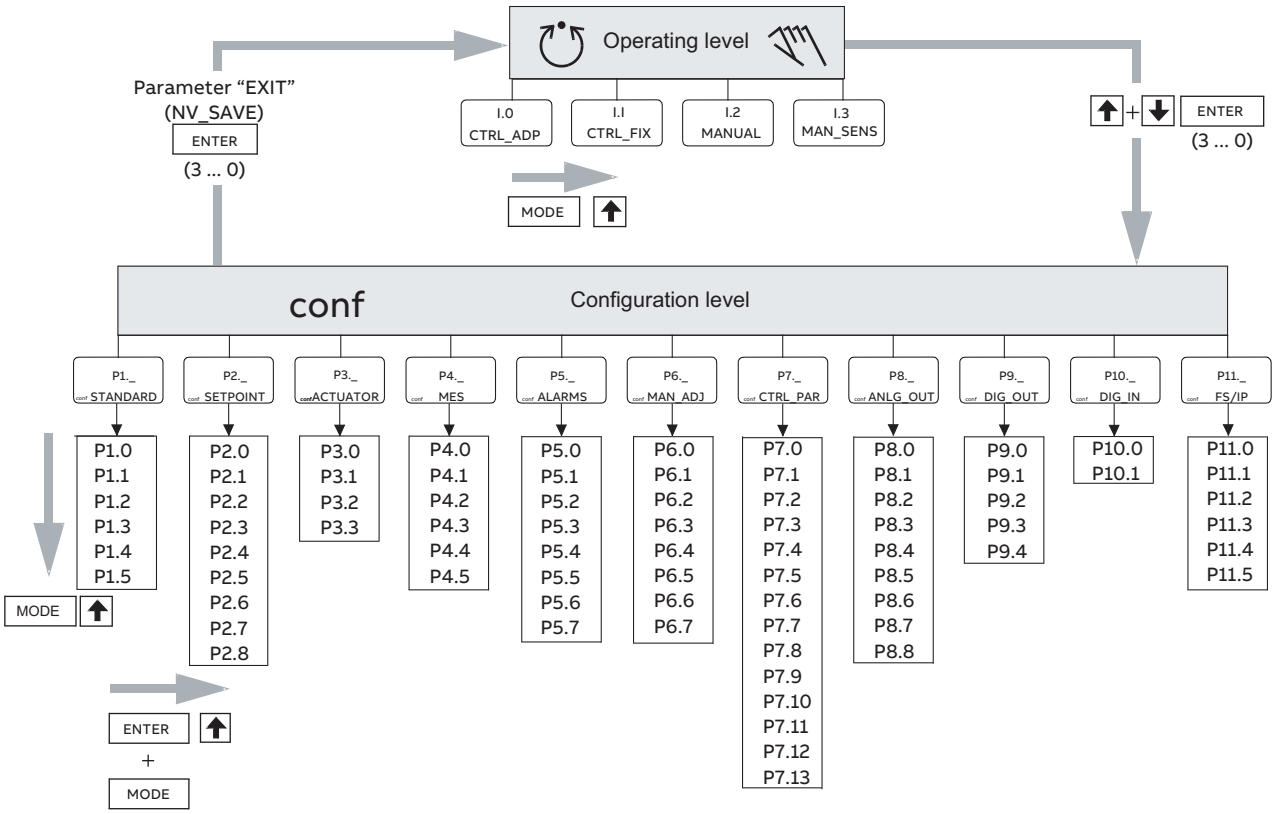


Figure 26: HART® Parameter Overview

Parameter description HART®

Parameter	Display	Function		Possible parameter setting	Unit	Factory setting
P1._	**STANDARD**					
P1.0	**ACTUATOR**	Actuator type	Actuator type	LINEAR, ROTARY	---	LINEAR
P1.1	**AUTO_ADJ**	Automatic adjustment	Autoadjust	Function	---	---
P1.2	**ADJ_MODE**	Auto adjust mode	Automatic adjustment mode	FULL,STROKE,CTRL_PAR, ZERO_POS, LOCKED		FULL
P1.3	**TEST**	Test	Test	Function	---	INACTIVE
P1.4	**FIND_DEV**	Find device	Find device	DISABLE, ONE TIME, CONTINOUS	---	DISABLE
P1.5	**EXIT**	Return	Return to operating level	Function	---	NV_SAVE
P2._	**SETPOINT**					
P2.0	**MIN_RGE**	Min setpoint range	Min. setpoint range	4.0 to 18.4	mA	4.0
P2.1	**MAX_RGE**	Max setpoint range	Max. setpoint range	20.0 to 5.6	mA	20.0
P2.2	**CHARACT**	Charact. curve	Characteristic curve	LINEAR, 1:25, 1:50, 25:1, 50:1, USERD	---	LINEAR
P2.3	**ACTION**	Valve action	Direction of action	DIRECT, REVERSE	---	DIRECT
P2.4	**SHUT_CLS**	Shut-off value 0%	Shut-off value 0 %	OFF, 0.1 to 45.0	%	1.0
P2.5	**SHUT_OPN**	Shut off value 100%	Shut-off value 100%	55.0 to 100.0, OFF	%	OFF
P2.6	**RAMP UP**	Set point ramp, up	Setpoint ramp (up)	OFF, 0 to 200	---	OFF
P2.7	**RAMP DN**	Set point ramp, down	Setpoint ramp (down)	OFF, 0 to 200	---	OFF
P2.8	**EXIT**	Return	Return to operating level	Function	---	NV_SAVE
P3._	**ACTUATOR**					
P3.0	**MIN_RGE**	Min. of stroke range	Operating range, min.	0.0 to 90.0	%	0.0
P3.1	**MAX_RGE**	Max. of stroke range	Operating range, max.	100.0 to 10.0	%	100
P3.2	**ZERO_POS**	Zero position	Zero position	CLOCKWISE, CTCLOCKWISE	---	CTCLOCKWISE
P3.3	**EXIT**	Return	Return to operating level	Function	---	NV_SAVE
P4._	**MESSAGES**					
P4.0	**TIME_OUT**	Control time out	Dead band time limit	OFF, to 200	---	OFF
P4.1	**POS_SW1**	Position switch 1	Switching point SW1	0.0 to 100.0	%	0.0
P4.2	**POS_SW2**	Position switch 2	Switching point SW2	0.0 to 100.0	%	100.0
P4.3	**SW1_ACTV**	Switchpoint 1 enable	Active direction SW1	FALL_BEL, EXCEED	---	FALL_BEL
P4.4	**SW2_ACTV**	Switchpoint 2 enable	Active direction SW2	FALL_BEL, EXCEED	---	EXCEED
P4.5	**EXIT**	Return	Return to operating level	Function	---	NV_SAVE
P5._	**ALARMS**					
P5.0	**LEAKAGE**	Leakage detection	Leakage to actuator	ACTIVE, INACTIVE	---	INACTIVE
P5.1	**SP_RGE**	Setpoint rng monitor	Outside the setpoint range	ACTIVE, INACTIVE	---	INACTIVE
P5.2	**SENS_RGE**	Sens. range monitor	Operating range exceeded	ACTIVE, INACTIVE	---	INACTIVE
P5.3	**CTRLER**	Controller monitor	Controller inactive	ACTIVE, INACTIVE	---	INACTIVE
P5.4	**TIME_OUT**	Control time out	Dead band time limit	ACTIVE, INACTIVE	---	INACTIVE
P5.5	**STRK_CTR**	Stroke counter	Movement counter	ACTIVE, INACTIVE	---	INACTIVE
P5.6	**TRAVEL**	Travel counter	Travel counter	ACTIVE, INACTIVE	---	INACTIVE
P5.7	**EXIT**	Return	Return to operating level	Function	---	NV_SAVE

… 8 Operation

… Parameter description HART®

Parameter	Display	Function		Possible parameter setting	Unit	Factory setting
P6._	**MAN_ADJ**					
P6.0	**MIN_VR**	Min. valve range	Operating range, min.	0.0 to 100.0	%	0
P6.1	**MAX_VR**	Max. valve range	Operating range, max.	0.0 to 100.0	%	100
P6.2	**ACTUATOR**	Actuator type	Actuator type	LINEAR, ROTARY	---	LINEAR
P6.3	**SPRNG_Y2**	Spring action (Y2)	Spring action (Y2)	CLOCKWISE, CTCLOCKWISE	---	CTCLOCKWISE
P6.4	**DANG_DN**	Dead angle close	Dead angle 0 %	0.0 to 45.0	%	0.0
P6.5	**DANG_UP**	Dead angle open	Dead angle 100%	55.0 to 100.0	%	100.0
P6.6	**BOLT_POS**	Bolt position	Actuator position	LEVER, STEM	---	LEVER
P6.7	**EXIT**	Return	Return to operating level	Function	---	NV_SAVE
P7._	**CTRL_PAR**					
P7.0	**KP UP**	KP value, up	KP value (up)	0.1 to 120.0	---	5.0
P7.1	**KP DN**	KP value, down	KP value (down)	0.1 to 120.0	---	5.0
P7.2	**TV UP**	TV value, up	TV value (up)	10 to 450	---	200
P7.3	**TV DN**	TV value, down	TV value (down)	10 to 450	---	200
P7.4	**Y-OFS UP**	Y offset, up	Y offset (up)	0.0 to 100.0	%	48.0
P7.5	**Y-OFS DN**	Y offset, down	Y offset (down)	0.0 to 100.0	%	48.0
P7.6	**TOL_BAND**	Tolerance band (zone)	Tolerance band (zone)	0.3 to 10.0	%	1.5
P7.7	**DEADBAND**	Deadband	Dead band	0.10 to 10.00	%	12:10 AM
P7.8	**DB_APPR**	Deadband Approach	Dead-band approach	SLOW, MEDIUM, FAST		
P7.9	**TEST**	Test	Test	Function	---	INACTIVE
P7.10	**DB_CALC**	Deadband calculat.	Dead-band determination	ON, OFF	---	ON
P7.11	**LEAK_SEN**	Leakage sensivity	Leakage sensitivity	1 to 7200	S	30
P7.12	**CLOSE_UP**	Pos. time out	Position monitoring	0.0 to 100.0	%	30.0
P7.13	**EXIT**	Return	Return to operating level	Function	---	NV_SAVE

Parameter	Display	Function		Possible parameter setting	Unit	Factory setting
P8._	**ANLG_OUT**					
P8.0	**MIN_RGE**	Min. range	Min. current range	4.0 to 18.4	mA	4.0
P8.1	**MAX_RGE**	Max. range	Max. current range	20.0 to 5.7	mA	20.0
P8.2	**ACTION**	Action	Direction of action of characteristic curve	DIRECT, REVERSE	---	DIRECT
P8.3	**ALARM**	Alarm current	Alarm message	HIGH_CUR, LOW_CUR	---	HIGH_CUR
P8.4	**RB_CHAR**	Readback character.	Converted characters	DIRECT, RECALC		DIRECT
P8.5	**TEST**	Test	Test	Function	---	NONE
P8.6	**ALR_ENAB**	Alarm function enabled	Alarm via analog output	ON, OFF	---	ON
P8.7	**CLIPPING**	Current signal Signal clipping range	Extension of signal output to 3.8 to 20.5 mA	4.0 to 20.0; 3.8 to 20.5 mA	mA	4.0 bis 20.5
P8.8	**EXIT**	Return	Return to operating level	Function	---	---
P9._	**DIG_OUT**					
P9.0	**ALRM_LOG**	Alarm logic	Alarm output logic	ACTIVE_HI, ACTIVE_LO	---	ACTIVE_HI
P9.1	**SW1_LOG**	Switchpoint 1 logic	Logic SW1	ACTIVE_HI, ACTIVE_LO	---	ACTIVE_HI
P9.2	**SW2_LOG**	Switchpoint 2 logic	Logic SW2	ACTIVE_HI, ACTIVE_LO	---	ACTIVE_HI
P9.3	**TEST**	Test	Test	Function	---	NONE
P9.4	**EXIT**	Return	Return to operating level	Function	---	NV_SAVE
P10._	**DIG_IN**					
P10.0	**FUNCTION**	Function select	Function selection	NONE, POS_0 %, POS_100 %, POS_HOLD	---	NONE
P10.1	**EXIT**	Return	Return to operating level	Function	---	---
P11._	**FS / IP**					
P11.0	**FAIL_POS**	Save position	Safe position	ACTIVE, INACTIVE	---	INACTIVE
P11.1	**FACT_SET**	Factory setting	Factory setting	Function	---	START
P11.2	**IP-TYP**	I/P module type	Type of I/P module	NO_F_POS,F_SAFE_1,F_SAFE_2, F_FREEZE1, F_FREEZE2	---	[CUSTOM]
P11.3*	**IP_COMP**	IP compensation	IP compensation	ON, OFF	---	ON
P11.4	**HART_REV**	HART revision	HART revision	5; 7	---	5
P11.5	**EXIT**	Return	Return to operating level	Function	---	NV_SAVE

* Activation by ABB Service only

Note

For detailed information on the parameterization of the device, consult the associated configuration and parameterization instructions.

9 Diagnosis / error messages

Error codes

Error code	Possible cause	Impact	Troubleshooting the Instrument
ERROR 10	The supply voltage was interrupted for at least 20 ms. (This error is displayed after resetting the device to indicate the reason for the reset.)	—	Check the power source and the wiring.
ERROR 11	The supply voltage has fallen below the minimum voltage.	The actuator is moved to the safe position. After approx. 5 seconds, the positioner is automatically reset and starts up again with the message **ERROR 10**. If a local communication interface (LCI) is plugged in, the device will enter the operating mode LCI supply.	Check the power source and the wiring.
ERROR 12	The position is outside the measuring range. Possible reason is a malfunction in the position sensor.	**In control mode:** • The actuator is moved to the safe position. **On the configuration level:** • The output is set to neutral until a button is pressed. After approx. 5 seconds the positioner is automatically reset in control mode and on the configuration level.	Check the mounting.
ERROR 13	Invalid input current. This display indicates when the setpoint signal is overridden. The actuator is moved to the safe position.	—	Check the power source and the wiring.
ERROR 20	No access possible to the data in the EEPROM.	The actuator is moved to the safe position. After approx. 5 seconds, the positioner is automatically reset. Attempts are made to restore the data. This compensates for intermittent errors in the communication environment with the EEPROM.	If there is still no access to the EEPROM data after resetting the device, load the factory settings. If the error still persists, the device must be returned for repair to the manufacturer.

Error code	Possible cause	Impact	Troubleshooting the Instrument
ERROR 21	Error while processing the measured values, pointing to an error in the working data (RAM).	The actuator is moved to the safe position. After approx. 5 seconds, the positioner is automatically reset and the RAM is reinitialized.	If the error persists even after the positioner has been reset, the device will need to be returned to the manufacturer for repair.
ERROR 22	Error during the table processing, pointing to an error in the working data (RAM).	The actuator is moved to the safe position. After approx. 5 seconds, the positioner is automatically reset and the RAM is reinitialized.	If the error persists even after the positioner has been reset, the device will need to be returned to the manufacturer for repair.
ERROR 23	Error when verifying the checksum of the configuration data (RAM).	The actuator is moved to the safe position. After approx. 5 seconds, the positioner is automatically reset and the RAM is reinitialized.	If the error persists even after the positioner has been reset, the device will need to be returned to the manufacturer for repair.
ERROR 24	Error in the processor function registers (RAM).	The actuator is moved to the safe position. After approx. 5 seconds, the positioner is automatically reset and the RAM is reinitialized.	If the error persists even after the positioner has been reset, the device will need to be returned to the manufacturer for repair.
ERROR 50 ⋮ ERROR 99	Internal error.	The actuator is moved to the safe position. After approx. 5 seconds, the positioner is automatically reset.	If the error can be reproduced and occurs in the same position after resetting, the device must be returned for repair to the manufacturer.

… 9 Diagnosis / error messages

Alarm codes

Alarm code	Possible cause	Impact	Troubleshooting the Instrument
ALARM 1	Leakage between positioner and actuator	Depending on how well the leakage can be compensated, small control actions are required at regular intervals.	Check the piping.
ALARM 2	The setpoint current is outside the permissible range, i.e. it is < 3.8 mA or > 20.5 mA.	–	Check the power source.
ALARM 3	Alarm of the zero monitor. The zero position has shifted by more than 4 %.	– In control mode, a position outside the valve range can only be reached by moving to the limit stops, as the setpoint is limited from 0 to 100 %	Correct the mounting.
ALARM 4	Controlling is inactive, because the device does not operate in control mode or the binary input is active.	The controller does not follow the setpoint.	Switch to control mode or switch off the binary input.
ALARM 5	Positioning timed out. The settling time needed exceeds the configured stroke time.	None, or adaptive control is performed (in adaptive mode).	Ensure that • the actuator is not blocked. • the supply air pressure is adequately high. • the specified time limit is higher than 1.5 times the longest stroke time of the actuator. If adaption cannot run uninterruptedly for an actuator, adaption should be switched on until the alarm does not occur anymore during controlling actions.
ALARM 6	The defined limit value for the stroke counter has been exceeded.	–	Reset the counter (only possible via a connected PC with suitable software).
ALARM 7	The specified limit value for the travel counter has been exceeded.	–	Reset the counter (only possible via a connected PC with suitable software).

Message codes

Message codes	Message description
BREAK	Action stopped by operator.
CALC_ERR	Error during plausibility check.
COMPLETE	Action completed, acknowledgment required.
EEPR_ERR	Memory error, data could not be saved.
FAIL_POS	Safe position is active, action cannot be executed.
NO_F_POS	Safe position required, but not active.
NO_SCALE	Valve range limits have not yet been determined; therefore, partial Autoadjust cannot be run.
NV_SAVE	Data is saved in the non-volatile memory.
OUTOFRNG	Measuring range is exceeded, Auto Adjust was automatically stopped.
LOAD	Data (factory settings) are being loaded.
RNG_ERR	Less than 10 % of the measuring range is used.
RUN	Action running.
STMUL	Simulation has been started externally from a PC via HART® protocol; switch outputs, alarm output and analog position feedback are no longer influenced by the process.
SPR_ERR	Actual spring action is different from the adjusted one.
TIMEOUT	Time-out; parameter could not be determined within two minutes; Autoadjust was automatically stopped.

10 Maintenance

The positioner does not require any maintenance if it is used as intended under normal operating conditions.

Note
Manipulation by users shall immediately render the warranty for the device invalid.
To ensure fault-free operation, it is essential that the device is supplied with instrument air that is free of oil, water, and dust.

11 Repair

Repair and maintenance activities may only be performed by authorized customer service personnel.
When replacing or repairing individual components, use original spare parts.

Returning devices

Use the original packaging or a secure transport container of an appropriate type if you need to return the device for repair or recalibration purposes.
Fill out the return form (see **Return form** on page 45) and include this with the device.
In accordance with the EU Directive governing hazardous materials, the owner of hazardous waste is responsible for its disposal or must observe the following regulations for shipping purposes:
All devices delivered to ABB must be free from any hazardous materials (acids, alkalis, solvents, etc.).

Please contact Customer Center Service acc. to page 4 for nearest service location.

12 Recycling and disposal

Note

Products that are marked with the adjacent symbol may **not** be disposed of as unsorted municipal waste (domestic waste).
They should be disposed of through separate collection of electric and electronic devices.

This product and its packaging are manufactured from materials that can be recycled by specialist recycling companies.

Bear the following points in mind when disposing of them:

- As of 8/15/2018, this product will be under the open scope of the WEEE Directive 2012/19/EU and relevant national laws (for example, ElektroG – Electrical Equipment Act - in Germany).
- The product must be supplied to a specialist recycling company. Do not use municipal waste collection points. These may be used for privately used products only in accordance with WEEE Directive 2012/19/EU.
- If there is no possibility to dispose of the old equipment properly, our Service can take care of its pick-up and disposal for a fee.

13 Additional documents

Note
All documentation, declarations of conformity and certificates are available in ABB's download area.
www.abb.com/positioners

14 Appendix

Return form

Statement on the contamination of devices and components

Repair and/or maintenance work will only be performed on devices and components if a statement form has been completed and submitted.
Otherwise, the device/component returned may be rejected. This statement form may only be completed and signed by authorized specialist personnel employed by the operator.

Customer details:

Company:

Address:

Contact person: Telephone:

Fax: Email:

Device details:

Type: Serial no.:

Reason for the return/description of the defect:

Was this device used in conjunction with substances which pose a threat or risk to health?

☐ Yes ☐ No

If yes, which type of contamination (please place an X next to the applicable items):

☐ biological ☐ corrosive / irritating ☐ combustible (highly / extremely combustible)

☐ toxic ☐ explosive ☐ other toxic substances

☐ radioactive

Which substances have come into contact with the device?

1.

2.

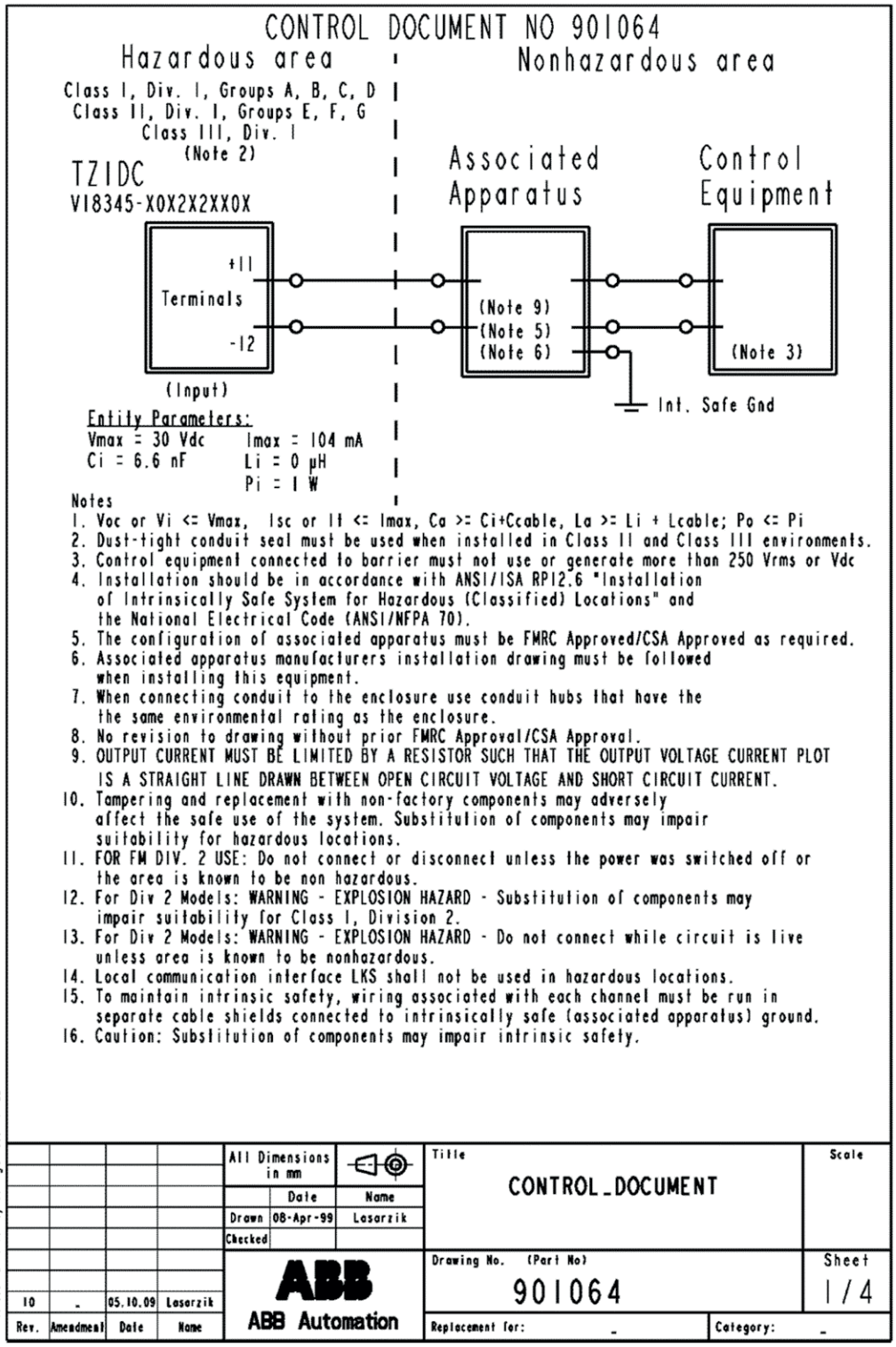
3.

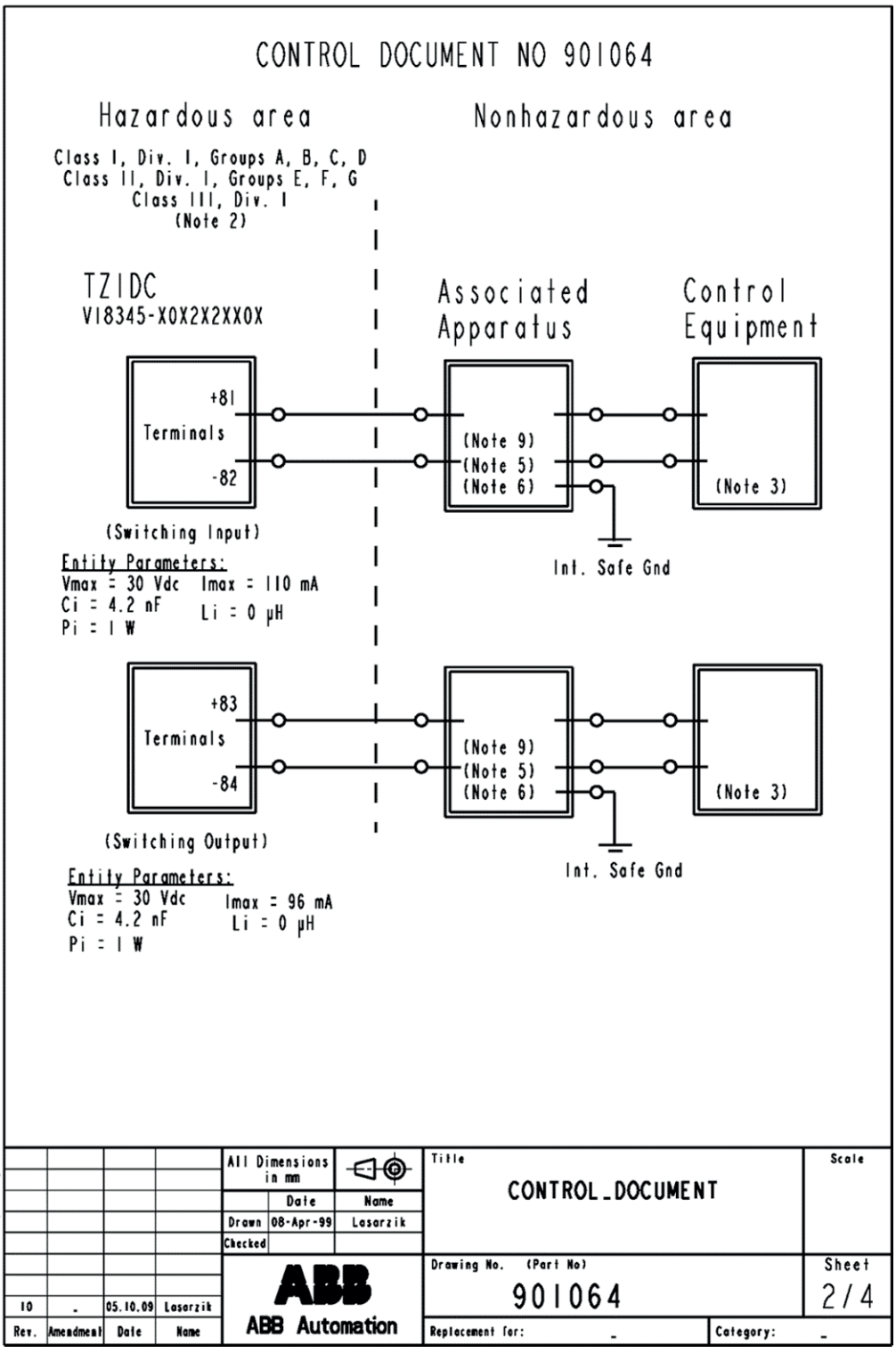
We hereby state that the devices/components shipped have been cleaned and are free from any dangerous or poisonous substances.

Town/city, date Signature and company stamp

... 14 Appendix

FM installation drawing No. 901064





Rev.	Amendment	Date	Name
10	-	05.10.09	Lasarzik

All Dimensions in mm

	Date	Name
Drawn	08-Apr-99	Lasarzik
Checked		

ABB Automation

Title: CONTROL_DOCUMENT

Scale:

Drawing No. (Part No): 901064

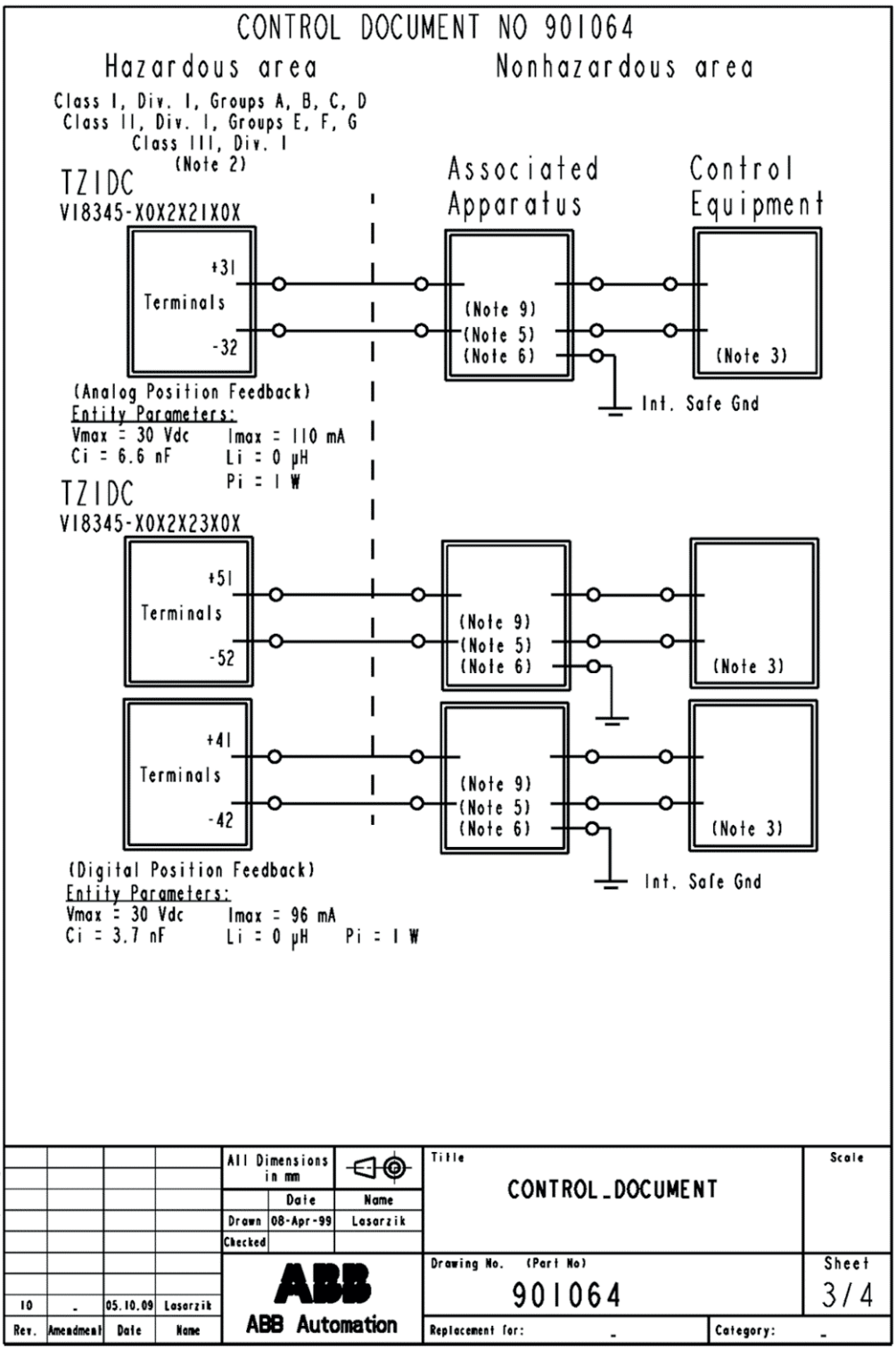
Sheet: 2/4

Replacement for: -

Category: -

… 14 Appendix

… FM installation drawing No. 901064



Rev.	Amendment	Date	Name
10	-	05.10.09	Lasarzik

All Dimensions in mm

	Date	Name
Drawn	08-Apr-99	Lasarzik
Checked		

ABB Automation

Title: CONTROL_DOCUMENT

Scale:

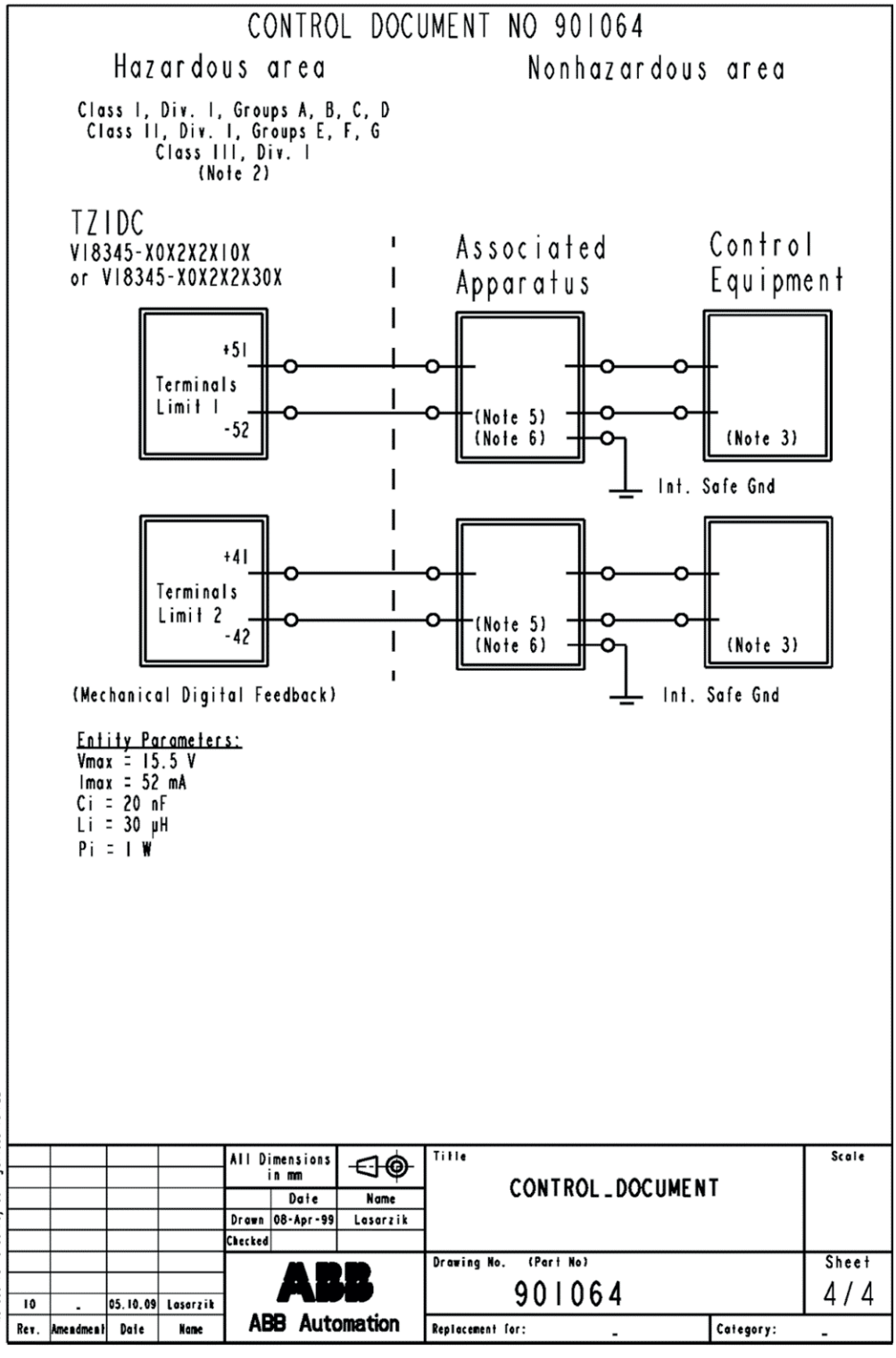
Drawing No. (Part No): 901064

Sheet: 3/4

Replacement for: -

Category: -

CONTROL DOCUMENT NO 901064



Entity Parameters:
Vmax = 15.5 V
Imax = 52 mA
Ci = 20 nF
Li = 30 µH
Pi = 1 W

Rev.	Amendment	Date	Name
10	-	05.10.09	Lasarzik

All Dimensions in mm

	Date	Name
Drawn	08-Apr-99	Lasarzik
Checked		

ABB Automation

Title: CONTROL_DOCUMENT

Scale:

Drawing No. (Part No): 901064

Sheet: 4/4

Replacement for: -

Category: -

Trademarks

HART is a registered trademark of FieldComm Group, Austin, Texas, USA

Notes

ABB Limited
Measurement & Analytics
Howard Road, St. Neots
Cambridgeshire, PE19 8EU
UK
Tel: +44 (0)870 600 6122
Fax: +44 (0)1480 213 339
Email: enquiries.mp.uk@gb.abb.com

ABB Automation Products GmbH
Measurement & Analytics
Schillerstr. 72
32425 Minden
Germany
Tel: +49 571 830-0
Fax: +49 571 830-1806

ABB Inc.
Measurement & Analytics
125 E. County Line Road
Warminster, PA 18974
USA
Tel: +1 215 674 6000
Fax: +1 215 674 7183

abb.com/positioners

3KXE341201R4201

OI/TZIDC-EN Rev. B 07.2018